PXI Express

NI PXIe-8135 User Manual
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This hardware has been tested and found to comply with the applicable regulatory requirements and limits for electromagnetic compatibility (EMC) as indicated in the hardware’s Declaration of Conformity (DoC)\(^1\). These requirements and limits are designed to provide reasonable protection against harmful interference when the hardware is operated in the intended electromagnetic environment. In special cases, for example when either highly sensitive or noisy hardware is being used in close proximity, additional mitigation measures may have to be employed to minimize the potential for electromagnetic interference.

While this hardware is compliant with the applicable regulatory EMC requirements, there is no guarantee that interference will not occur in a particular installation. To minimize the potential for the hardware to cause interference to radio and television reception or to experience unacceptable performance degradation, install and use this hardware in strict accordance with the instructions in the hardware documentation and the DoC\(^1\).

If this hardware does cause interference with licensed radio communications services or other nearby electronics, which can be determined by turning the hardware off and on, you are encouraged to try to correct the interference by one or more of the following measures:

• Reorient the antenna of the receiver (the device suffering interference).
• Relocate the transmitter (the device generating interference) with respect to the receiver.
• Plug the transmitter into a different outlet so that the transmitter and the receiver are on different branch circuits.

Some hardware may require the use of a metal, shielded enclosure (windowless version) to meet the EMC requirements for special EMC environments such as, for marine use or in heavy industrial areas. Refer to the hardware’s user documentation and the DoC\(^1\) for product installation requirements.

When the hardware is connected to a test object or to test leads, the system may become more sensitive to disturbances or may cause interference in the local electromagnetic environment.

Operation of this hardware in a residential area is likely to cause harmful interference. Users are required to correct the interference at their own expense or cease operation of the hardware.

\[\text{Caution}\] Changes or modifications not expressly approved by National Instruments could void the user’s right to operate the hardware under the local regulatory rules. To ensure the specified EMC performance, operate this product only with shielded cables and accessories.

\(^1\) The Declaration of Conformity (DoC) contains important EMC compliance information and instructions for the user or installer. To obtain the DoC for this product, visit ni.com/certification, search by model number or product line, and click the appropriate link in the Certification column.
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About This Manual

This manual contains detailed instructions for installing and configuring the National Instruments PXIe-8135 embedded computer kit.

How to Use the Documentation Set

Begin by reading the NI PXIe-8135 Installation Guide, a brief quick-start guide that describes how to install and get started with your controller.

This manual, the NI PXIe-8135 User Manual, contains more details about changing the installation or configuration from the defaults and using the hardware.

Related Documentation

The following documents contain information you may find helpful as you read this manual:

• PICMG EXP.0 R1.0 CompactPCI Express Specification, PCI Industrial Computers Manufacturers Group
• PCI Express Base Specification, Revision 2.1, PCI Special Interest Group
• PXI-5 PXI Express Hardware Specification, Revision 1.0, PXI Systems Alliance
• PXI-6 PXI Express Software Specification, Revision 1.1, PXI Systems Alliance
• Serialized IRQ Support for PCI Systems Specification, Revision 6.0, Compaq Computer et al.
• ExpressCard Standard, Release 2.0, PCMCIA
Introduction

This chapter provides overview information for PXI Express and the NI PXIe-8135 embedded controller.

Benefits of PXI Express

The PXI (PCI eXtensions for Instrumentation) industry standard, an open specification governed by the PXI Systems Alliance (PXISA), has quickly gained adoption and grown in prevalence in test, measurement, and control systems since its release in 1998. One of the key elements driving the rapid adoption of PXI is its use of PCI in the communication backplane. As the commercial PC industry has improved the available bus bandwidth by evolving PCI to PCI Express, PXI is now able to meet even more application needs by integrating PCI Express into the PXI standard. By taking advantage of PCI Express technology in the backplane, PXI Express increases the available PXI bandwidth from up to 132 MB/s to up to 8 GB/s for a more than 60x improvement in bandwidth.

PXI Express maximizes both hardware and software compatibility with PXI modules. PXI Express hybrid slots deliver both PCI and PCI Express signaling to accept devices that use PXI communication and triggering or the newer PXI Express standard. Software compatibility is maintained because PCI Express uses the same OS and driver model as PCI, resulting in complete software compatibility among PCI-based systems, for example PXI, and PCI Express-based systems such as PXI Express.

PXI Express, like PXI, leverages from the CompactPCI specification to define a rugged, modular form factor that offers superior mechanical integrity and easy installation and removal of hardware components. PXI Express products offer higher and more carefully defined levels of environmental performance required by the shock, vibration, temperature, and humidity extremes of industrial environments. Mandatory environmental testing and active cooling is added to the CompactPCI mechanical specification to ease system integration and ensure multivendor interoperability.

The demanding timing and synchronization requirements of instrumentation systems are met by the integrated features of PXI Express. Not only are the trigger bus, 10 MHz system reference clock, and star trigger bus available in PXI retained by PXI Express, but new timing and synchronization features that include a 100 MHz differential system reference clock for the synchronization of multiple modules and three differential star trigger buses for the distribution of precise clock and trigger signals have been added. Differential timing and synchronization signals provide PXI Express systems with increased noise immunity and the ability to transmit clock signals at higher frequencies.
Chapter 1  Introduction

NI PXIe-8135

Description
The NI PXIe-8135 PXI Express/CompactPCI Express embedded computer is a high bandwidth PXI Express/CompactPCI Express-compatible system controller. The NI PXIe-8135 controller integrates standard I/O features in a single unit by using state-of-the-art packaging. Combining an NI PXIe-8135 embedded controller with a PXI Express-compatible chassis, such as the NI PXIe-1085, results in a fully PC-compatible computer in a compact, rugged package.

The standard I/O on each module includes two DisplayPort video ports, one RS-232 serial port, a parallel port, four high-speed USB 2.0 ports, two high-speed USB 3.0 ports, a PCI-based GPIB controller, two Gigabit Ethernet connectors, a reset button, and PXI Express triggers.

The NI PXIe-8135 has a quad-core Intel Core i7-3610QE processor, dual channel DDR3, 1600 MHz memory controller, all the standard I/O, and an integrated hard drive.

Note  The removable hard drive variant has single channel DDR3.

The NI PXIe-8135 also has an optional ExpressCard/34 expansion slot variant, and an optional front panel-accessible, removable hard drive.

Functional Overview
This section contains functional descriptions of each major logic block on the NI PXIe-8135 embedded computer.
NI PXIe-8135 Functional Description

The NI PXIe-8135 is a modular PC in a PXI Express 3U-size form factor. Figure 1-1 is a functional block diagram of the NI PXIe-8135. Following the diagram is a description of each logic block shown.

Figure 1-1. NI PXIe-8135 Block Diagram

The NI PXIe-8135 consists of the following logic blocks on the CPU module and the I/O (daughter card) module. The CPU module has the following logic blocks:

- The SO-DIMM block consists of two 64-bit DDR3 SDRAM sockets that can hold up to 8 GB each, for a total of 16 GB.

  Note  The NI PXIe-8135 removable hard drive variant has a single SDRAM socket, for a total of up to 8 GB.

- The SMB to PXI Express Trigger provides a routable connection of the PXI Express triggers to/from the SMB on the front panel.
- The ATI Radeon E4690 Embedded GPU drives the graphics.
Chapter 1  Introduction

• The Watchdog Timer block consists of a watchdog timer that can reset the controller or generate a trigger.

• The Intel 7 Series chipset connects to the PCI, USB, Serial ATA, ExpressCard, PXI Express, and LPC buses.

• The USB Connectors connect the Intel 7 Series chipset to the Hi-Speed USB 2.0 interface and USB 3.0 interfaces.

• The Serial ATA Hard Disk is a 250 GB or larger notebook hard disk.\(^1\) The Serial ATA interface enables transfer rates up to 600 MB/s. The hard disk also supports Native Command Queuing.

\[\text{Note}\quad \text{The NI PXIe-8135 removable hard drive Serial ATA interface enables transfer rates up to 300 MB/s.}\]

• The PXI Express Connector connects the NI PXIe-8135 to the PXI Express/CompactPCI Express backplane.

• The Super I/O block represents the other peripherals supplied by the NI PXIe-8135. The NI PXIe-8135 has one serial port, and an ECP/EPP parallel port.

• Both the 82579 and 82574 Gigabit Enet ports connect to either 10 Mbit, 100 Mbit, or 1,000 Mbit Ethernet interfaces. Both ports are housed in a dual stacked Ethernet connector.

• The GPIB block contains the GPIB interface.

• The ExpressCard/34 slot accommodates an ExpressCard/34 module.

National Instruments Software

National Instruments has developed several software tools you can use with the NI PXIe-8135.

National Instruments’ hardware and software work together to help you make the most of your PXI Express system. The LabVIEW, Measurement Studio, and LabWindows™/CVI™ application development environments combine with leading hardware drivers such as NI-DAQmx to provide exceptional control of NI hardware. Instrument drivers are available at ni.com/idnet to simplify communication with instruments over a variety of buses.

LabVIEW is a powerful and easy-to-use graphical programming environment you can use to acquire data from thousands of different instruments including USB, IEEE 488.2, VXI, serial, PLCs, and plug-in boards. LabVIEW helps you convert acquired data into meaningful results using powerful data analysis routines. Add-on tools provide additional specialized functionality. For more information visit ni.com/labview and ni.com/toolkits.

If you prefer to use Microsoft’s Visual Basic, Visual C++, and Visual Studio .NET for the core of your application, Measurement Studio adds tools for Measurement and Automation to each language. For more information visit ni.com/mstudio.

\(^1\) The extended-temperature, 24/7 option controller provides a 80 GB hard drive.
LabWindows/CVI is an interactive ANSI C programming environment designed for building virtual instrument applications. LabWindows/CVI delivers a drag-and-drop editor for building user interfaces, a complete ANSI C environment for building your test program logic, and a collection of automated code generation tools, as well as utilities for building automated test systems, monitoring applications, or laboratory experiments. For more information visit ni.com/lwcvi.

NI-DAQmx provides an extensive library of functions that you can call from your application development environment or interactive environment such as NI Signal Express. These functions provide an intuitive API for National Instruments' multifunction DAQ products. Features available include analog input (A/D conversion), buffered data acquisition (high-speed A/D conversion), analog output (D/A conversion), waveform generation, digital I/O, counter/timer operations, SCXI signal conditioning, RTSI or PXI Express synchronization, self-calibration, messaging, and acquiring data to extended memory. For more information visit ni.com/daq.

National Instruments’ Modular Instruments use specialized drivers suited to each product’s specialization. Express VIs provide customized, interactive programming of instruments in a single interface and soft front panels provide an interface for testing the functionality of each instrument with no programming required. NI Switches, DMMs, High-Speed DIO, High-Speed Digitizers, and Sources each have customized drivers for high-end modular instrumentation systems. RF applications leverage two drivers, NI-RFSG and NI-RFSA and Dynamic Signal Acquisition is available through NI-DAQmx. For more information visit ni.com/modularinstruments.

You can expand the timing and triggering functionality of your PXI Express system with PXI Express Timing and Synchronization products. These products provide precision clock sources, custom routing of triggers for multi-chassis synchronization, clock sharing, and more and are programmed with NI-Sync. For more information visit ni.com/pxi.

NI-VISA is the National Instruments implementation of the VISA specification. VISA is a uniform API for communicating and controlling USB, Serial, GPIB, PXI, PXI Express, VXI, and various other types of instruments. This API aids in the creation of portable applications and instrument drivers. For information on writing your own PXI Express instrument driver with NI-VISA, refer to the NI-VISA Getting Started Manual and the readme.txt file in the NI-VISA directory. For more information visit ni.com/visa.

With LabVIEW for Linux and support for over two hundred devices on Linux with the NI-DAQmx driver, you can now create Virtual Instruments based on the Linux OS. Instrument control in Linux has been improved by the NI-VISA driver for Linux and NI Modular Instruments are partially supported. For more information visit ni.com/linux.

Cleaning

Use a dry, low-velocity stream of air to clean the NI PXIe-8135 controller. If needed, use a soft-bristle brush for cleaning around components.
Installation and Configuration

This chapter contains information about installing and configuring your NI PXIe-8135 controller.

Installing the NI PXIe-8135

This section contains general installation instructions for the NI PXIe-8135. Consult your PXI Express chassis user manual for specific instructions and warnings.

1. Plug in your chassis before installing the NI PXIe-8135. The power cord grounds the chassis and protects it from electrical damage while you install the module.

   Caution  To protect both yourself and the chassis from electrical hazards, leave the chassis powered off until you finish installing the NI PXIe-8135 module.

2. Remove any filler panels blocking access to the system controller slot (Slot 1) in the chassis.

3. Touch the metal part of the case to discharge any static electricity that might be on your clothes or body.
4. Remove the protective plastic covers from the four bracket-retaining screws as shown in Figure 2-1.

![Figure 2-1. Removing Protective Screw Caps](image)

5. Make sure the injector/eject or handle is in its downward position. Align the NI PXIe-8135 with the card guides on the top and bottom of the system controller slot.

**Caution** Do not raise the injector/ejector handle as you insert the NI PXIe-8135. The module will not insert properly unless the handle is in its downward position so that it does not interfere with the injector rail on the chassis.

6. Hold the handle as you slowly slide the module into the chassis until the handle catches on the injector/ejector rail.

7. Raise the injector/ejector handle until the module firmly seats into the backplane receptacle connectors. The front panel of the NI PXIe-8135 should be even with the front panel of the chassis.

8. Tighten the four bracket-retaining screws on the top and bottom of the front panel to secure the NI PXIe-8135 to the chassis.

9. Check the installation.
10. Connect the keyboard and mouse to the appropriate connectors. If you are using a PS/2 keyboard and a PS/2 mouse, a Y-splitter adapter is available to connect both to a single USB connector. Refer to Figure 4-1, Y-Splitter Cable.

11. Connect the DisplayPort monitor video cable to a DisplayPort connector, or use the DisplayPort-to-VGA adapter included with your controller to connect a VGA monitor to the DisplayPort connector.

12. Connect devices to ports as required by your system configuration.

13. Power on the chassis.

14. Verify that the controller boots. If the controller does not boot, refer to the What if the NI PXIe-8135 does not boot? section of Chapter 5, Troubleshooting.

Figure 2-2 shows an NI PXIe-8135 installed in the system controller slot of a National Instruments NI PXIe-1082 chassis.

**Figure 2-2. NI PXIe-8135 Controller Installed in a PXI Express Chassis**

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How to Remove the Controller from the PXI Express Chassis

The NI PXIe-8135 controller is designed for easy handling. To remove the unit from the PXI Express chassis, complete the following steps.

1. Power off the chassis.
2. Unscrew the 4 bracket-retaining screws in the front panel.
3. Press the injector/ejector handle down.
4. Slide the unit out of the chassis.
Note If the PXI Express chassis Inhibit Mode Selector Switch is not in the Default position, any attempt to shut down the NI PXIe-8135 through the push button reset or using Windows will result in the controller Power OK LED blinking. The user will be required to use the Remote Inhibit pin on the Remote Inhibit and Voltage Monitoring Connector to turn off the chassis. Refer to the PXI Express chassis user manual for details on the functionality of the Remote Inhibit and Voltage Monitoring controls.

BIOS Setup Utility

You can change the NI PXIe-8135 configuration settings in the BIOS setup program. The BIOS is the low-level interface between the hardware and operating system software that configures and tests your hardware when you boot the system. The BIOS setup program includes menus for configuring settings and enabling NI PXIe-8135 controller features.

Most users do not need to use the BIOS setup program, as the NI PXIe-8135 controller ships with default settings that work well for most configurations.

Caution Changing BIOS settings may lead to incorrect controller behavior and possibly an unbootable controller. If this happens, follow the instructions for restoring default settings in the System CMOS section. In general, do not change a setting unless you are absolutely certain what it does.

Accessing BIOS Setup Utility

Complete the following steps to start the BIOS setup program.

1. Power on or reboot your NI PXIe-8135 controller.
2. When the message Press <DEL> to enter setup appears, press the <Delete> key. The setup program loads after a short delay.

The Main menu is displayed when you first enter the BIOS setup program.

Use the following keys to navigate through the BIOS setup program:

- **Left Arrow, Right Arrow**—Use these keys to move between the different setup menus. If you are in a submenu, these keys have no effect, and you must press <Esc> to leave the submenu first. (To use the arrows on the numeric keypad, you must turn off Num Lock.)
- **Up Arrow, Down Arrow**—Use these keys to move between the options within a setup menu. (To use the arrows on the numeric keypad, you must turn off Num Lock.)
- **<Enter>**—Use this key either to enter a submenu or display all available settings for a highlighted configuration option.
- **<Esc>**—Use this key to return to the parent menu of a submenu. At the top-level menus, this key serves as a shortcut to the Exit menu.
- **<leftrightarrow> and <->**—Use these keys to cycle between all available settings for a selected configuration option.
• <Tab>—Use this key to select time and date fields.
• <F9>—Use this key to load the optimal default values for BIOS configuration settings. The optimal default values are the same as the shipping configuration default values.

Main Setup Menu
The most commonly accessed and modified BIOS settings are in the Main setup menu. The Main setup menu reports the following configuration information:

- **BIOS Version and Build Date**—These values indicate the version of the NI PXIe-8135 controller BIOS and the date on which the BIOS was built.
- **Embedded Firmware Version**—This value helps identify the built-in hardware capabilities.
- **Processor Type, Base Processor Frequency, and Active Processor Cores**—These values indicate the type of processor used in the NI PXIe-8135 controller, the speed of the processor, and the number of active processor cores.
- **Total Memory**—This value indicates the size of system RAM detected by the BIOS.
- **PXIe Chassis Information**—These values indicate the overall chassis link configuration, the link width of each link, and the link speed of each link.

The Main setup menu also includes the following settings:

- **System Time**—This setting controls the time of day, which is stored in a battery-backed real-time clock. Most operating systems also include a way to change this setting. Use <+> and <-> in conjunction with <Enter> and <Tab> to change these values.
- **System Date**—This setting controls the date, which is stored in a battery-backed real-time clock. Most operating systems also include a way to change this setting. Use <+> and <-> in conjunction with <Enter> and <Tab> to change these values.

Advanced Setup Menu
This menu contains BIOS settings that normally do not require modification. If you have specific problems such as unbootable disks or resource conflicts, you may need to examine these settings.

⚠️ **Caution** Changing settings in this menu may result in an unstable or unbootable controller. If this happens, follow the procedures outlined in the System CMOS section to restore BIOS settings to their factory defaults.

The Advanced setup menu includes the following settings and submenus:

- **SATA Configuration**—Use this setting to access the SATA Configuration submenu. Refer to the SATA Configuration Submenu section for more information.
- **CPU Configuration**—Use this setting to access the CPU Configuration submenu. Refer to the CPU Configuration Submenu section for more information.
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- **Video Configuration**—Use this setting to access the Video Configuration submenu. Refer to the Video Configuration Submenu section for more information.
- **Power/Wake Configuration**—Use this setting to access the Power/Wake Configuration submenu. Refer to the Power/Wake Configuration Submenu section for more information.
- **ExpressCard Configuration**—Use this setting to access the ExpressCard Configuration submenu. Refer to the ExpressCard Configuration Submenu section for more information.
- **PCI Configuration**—Use this setting to access the PCI Configuration submenu. Refer to the PCI Configuration Submenu section for more information.
- **Memory Configuration**—Use this setting to access the Memory Configuration submenu. Refer to the Memory Configuration Submenu section for more information.
- **AMT Configuration**—Use this setting to access the AMT Configuration submenu. Refer to the AMT Configuration Submenu section for more information.
- **USB Configuration**—Use this setting to access the USB Configuration submenu. Refer to the USB Configuration Submenu section for more information.
- **Serial/Parallel Port Configuration**—Use this setting to access the Serial/Parallel Port Configuration submenu. Refer to the Serial/Parallel Port Configuration Submenu section for more information.

**SATA Configuration Submenu**

Use this submenu to apply alternate settings to the hard disk drive (HDD) interfaces. Normally, you do not need to modify these settings, as the factory default settings provide the most compatible and optimal configuration possible.

- **SATA Controller**—This setting specifies whether or not the onboard SATA controller is enabled or disabled. The default value is **Enabled**.
  - **SATA Mode Selection**—This setting determines whether AHCI mode is enabled or disabled for the SATA port. Some operating systems, such as Windows 2000, do not support AHCI mode. You can use this setting to disable AHCI mode and enable IDE mode so that non-compatible OSes function correctly. The default value is **AHCI**.
- **Internal Drive (SATA)**—This item displays the onboard SATA drive detected in the system.
- **Removable Hard Drive**—This item displays the removable hard drive, if installed.

**CPU Configuration Submenu**

Use this submenu to apply alternate settings to the CPU. Normally, you do not need to modify these settings, as the factory default settings provide the most compatible and optimal configuration possible.

- **Hyper Threading**—This setting enables or disables Intel Hyper-Threading technology. The default value is **Enabled**. Enabling Hyper-Threading increases performance for some applications by adding virtual CPU cores. Hyper-Threading can increase application jitter, so care should be taken when enabling this setting on a Real Time system. When the BIOS
is configured to boot LabVIEW Real-Time, Hyper-Threading will be automatically disabled. In order to manually enable Hyper-Threading performance when in LabVIEW Real-Time mode, see the **LabVIEW RT Configuration Overrides Submenu**.

- **Enabled CPU Cores**—This setting selects the number of active CPU cores for the processor. Valid values are **All**, **3**, **2**, or **1**. The default value is **All**.

- **Turbo Boost**—This setting enables or disables Intel Turbo Boost technology. The default value is **Enabled**. Enabling Turbo Boost allows CPU cores to run at higher than their base frequency for short durations, while other cores are idle. Enabling Turbo Boost can also increase application jitter, so care should be taken when enabling this setting on a Real Time system. To achieve maximum possible Turbo Boost frequencies, also enable the C-States setting. When the BIOS is configured to boot LabVIEW Real-time, Turbo Boost will be automatically disabled. In order to manually enable Turbo Boost performance when in LabVIEW Real-Time mode, see the **LabVIEW RT Configuration Overrides Submenu**.

- **C-States**—This setting enables or disables CPU power management. The default value is **Enabled**. Enabling C-States allows the processor to put idle CPU cores to sleep, allowing active cores to run at higher than base frequencies when Turbo Boost is enabled. Enabling C-States can increase application jitter, so care should be taken when enabling this setting on a Real Time system. When the BIOS is configured to boot LabVIEW Real-time, C-States will be automatically disabled. In order to manually enable C-States when in LabVIEW Real-Time mode, see the **LabVIEW RT Configuration Overrides Submenu**.

- **Hardware Prefetcher**—This setting enables or disables CPU cache hardware prefetching. The default value is **Disabled** when booting LabVIEW Real-Time, enabled when booting other OSs. Enabling hardware prefetching can increase system performance for some applications, but can cause control algorithms to behave less deterministically.

- **Adjacent Cache Line Prefetch**—This setting enables or disables prefetching of adjacent cache lines from memory to the CPU cache. The default value is **Disabled** when booting LabVIEW Real-Time, enabled when booting other OSs. Enabling adjacent cache line prefetching can increase system performance for some applications, but can cause control algorithms to behave less deterministically.

**Video Configuration Submenu**

Use this submenu to apply alternate settings to the video configuration. Normally, you do not need to modify these settings, as the factory default settings provide the most compatible and optimal configuration possible.

- **Primary Display**—This setting specifies which video adapter the BIOS should use as the primary adapter if more than one is present. To use an external video adapter as the primary graphics adapter, choose **Add-in Board Video**. The default value is **Onboard ATI Video**.
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Power/Wake Configuration Submenu

Use this submenu to apply alternate configurations to the power and wake features of the chipset and controller. Normally, you do not need to modify these settings, as the factory default settings provide the most compatible and optimal configuration possible.

- **Restore After Power Loss**—This setting specifies the power state that the controller should return to after AC power is lost. Valid values are **Stay Off** and **Turn On**. The default is **Stay Off**. When set to **Stay Off**, the controller will return to the soft off power state after AC power is restored. When set to **Turn On**, the controller will power on when AC power is restored.

- **Power Button Off Behavior**—This setting specifies how the PXI Express power button should behave. Valid options are **Normal** and **Disable**. The default value is **Normal**. When set to **Normal**, the power button will be controlled by the OS. When set to **Disable**, pressing the power button has no effect. The **Disable** option should only be used in conjunction with the PXI Express chassis’ inhibit mode switch.

- **ExpressCard WAKE#**—This setting enables or disables an ExpressCard device’s ability to wake a powered-off system. The default value is **Disabled**.

- **PXIe Backplane WAKE#**—This setting enables or disables a PXI Express peripheral module’s ability to wake a powered-off system. The default value is **Disabled**.

- **SMBus ALERT#**—This setting enables or disables a System Management device’s ability to wake a powered-off system by asserting the ALERT# signal. The default value is **Disabled**.

ExpressCard Configuration Submenu

Use this submenu to apply alternate settings to the ExpressCard configuration. These settings determine how much memory space, I/O space, and PCI bus numbers will be pre-allocated for the ExpressCard port, allowing non-PCI Express-aware operating systems to support hot-plugging ExpressCard devices. Normally, you do not need to modify these settings, as the factory default settings provide the most compatible and optimal configuration possible.

- **ExpressCard Resources**—This setting enables or disables the setting of the **Reserved Buses**, **Reserved Memory**, and **Reserved I/O** settings. The default value for this setting is **Enabled**. If this setting is disabled, the bus, memory, and I/O options disappear from this submenu. Disabling this setting effectively sets **Reserved Buses** to 0, **Reserved Memory** to 0M, and **Reserved I/O** to 0K.

- **Reserved Buses**—This setting determines the number of PCI buses that will be reserved by the BIOS for ExpressCard PCI-PCI bridges that may be hot-plugged in the ExpressCard slot. The default value for this setting is 8 PCI buses.

- **Reserved Memory**—This setting determines the amount of memory space, in bytes, that will be reserved by the BIOS for PCI-PCI bridges that may be hot-plugged in the ExpressCard slot. The default value for this setting is 64M bytes of memory.

- **Reserved I/O**—This setting determines the amount of I/O space, in bytes, that will be reserved by the BIOS for PCI-PCI bridges that may be hot-plugged in the ExpressCard slot. The default value for this setting is 4K bytes of I/O space.
PCI Configuration Submenu

Use this submenu to apply alternate settings to PCI devices. Normally, you do not need to modify these settings, as the factory default settings provide the most compatible and optimal configuration possible.

- **64-bit Memory-Mapped IO**—This setting enables or disables support for memory-mapped IO above the 4 GB boundary. It can be useful when using a 64-bit OS and a large number of PCI devices. The default value is **Disabled**.

- **PCIe Max Payload Size**—This setting determines the maximum payload size of PCIe devices. Valid options are **Auto** and **128 Bytes**. The default value is **Auto**, which allows the BIOS to choose an optimal value based on which devices are present.

- **Option ROM Monitor**—This setting enables or disables a limit on option ROM execution time. The default value is **Disabled**.

- **Option ROM Monitor Timeout**—This setting specifies the number of seconds to wait for an option ROM to execute. If an option ROM does not execute in this time, the system will reboot. This setting is only visible if **Option ROM Monitor** is set to **Enabled**. The default value is 1 second.

Memory Configuration Submenu

Use this submenu to apply alternate settings to memory. Normally, you do not need to modify these settings, as the factory default settings provide the most compatible and optimal configuration possible.

- **Memory Performance Mode**—This setting enables or disables performance mode for memory. The default value is **Enabled**.

AMT Configuration Submenu

Use this submenu to apply alternate settings for Intel Advanced Management Technology (AMT) and its Management Engine. Normally, you do not need to modify these settings, as the factory default settings provide the most compatible and optimal configuration possible.

- **Management Engine Setup Prompt**—This setting enables or disables the Intel AMT Management Engine setup prompt on the BIOS POST screen. When this is set to Enabled, you will be allowed to press <Ctrl-P> at the BIOS POST screen to configure the Management Engine. The default value is **Disabled**.

- **Unconfigure Management Engine**—This setting allows the Management Engine to be reset to factory settings on the next boot. This option will revert to its default value after the Management Engine is reset. The default value is **Disabled**.

- **USB-Based Configuration**—This setting enables or disables automatic configuration of the Management Engine based on Management Engine configuration files which may be present on USB devices plugged into the controller. The default value is **Disabled**.
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USB Configuration Submenu

Use this submenu to apply alternate configurations to the USB ports. Normally, you do not need to modify these settings, as the factory default settings provide the most compatible and optimal configuration possible.

- **USB Devices**—This item lists the total number of devices detected in the system, categorized by device type.

- **Legacy USB Support**—This setting specifies whether or not legacy USB support is enabled. Legacy USB support refers to the ability to use a USB keyboard and mouse during system boot or in a legacy operating system such as DOS. The default value is **Enabled**. This option is automatically disabled when booting LabVIEW Real-Time in order to reduce application jitter.

- **Overcurrent Reporting**—This setting allows the BIOS to notify the operating system of any USB ports which sources too much current. The default value for this setting is **Disabled**.

- **Transfer Timeout**—This setting specifies the timeout value for Control, Bulk, and Interrupt USB transfers. The default value for this setting is **20** seconds.

- **Device Reset Timeout**—This setting specifies the number of seconds the Power-On Self Test will wait for a USB mass storage device to start. The default is **20** seconds.

- **Device Power-Up Delay**—This setting specifies the maximum time a device will take before it properly reports itself to the host controller. When set to **Auto**, a root port is granted 100 ms, and for a hub port, the delay value is taken from the hub descriptor. The default value for this setting is **Auto**.

- **Device Power-Up Delay in Seconds**—This setting specifies the number of seconds the Power-On Self Test will wait for a USB device or hub to power on. This setting is only visible if **Device Power-Up Delay** is set to **Manual**. The default is **5** seconds.

In addition, the following option is available for each detected device if a USB mass storage device is present:

- **Emulation Type**—This setting specifies how the BIOS will present the USB mass storage device to the system. This option can be used to present a USB mass storage device as a floppy, Zip, hard disk, or CD-ROM drive. The default is **Auto**, which allows the BIOS to treat small USB flash disk drives as floppy drives and larger USB flash disk drives as hard disk drives.

Serial/Parallel Port Configuration Submenu

Use this submenu to apply alternate configurations to the serial and parallel ports. Normally, you do not need to modify these settings, as the factory default settings provide the most compatible and optimal configuration possible.

- **Serial Port Configuration**—Use this setting to access the **Serial Port Configuration Submenu**. Refer to the **Serial Port Configuration Submenu** section for more information.

- **Parallel Port Configuration**—Use this setting to access the **Parallel Port Configuration Submenu**. Refer to the **Parallel Port Configuration Submenu** section for more information.
Serial Port Configuration Submenu

- **Serial Port**—This setting enables or disables the onboard serial port. The default value is **Enabled**.
- **Device Settings**—This item displays the current base address and interrupt request level (IRQ) information for the onboard serial port.
- **Change Settings**—This setting changes the base address and interrupt request level (IRQ) information for the onboard serial port. The default value is **Auto**.

Parallel Port Configuration Submenu

- **Parallel Port**—This setting enables or disables the onboard parallel port. The default value is **Enabled**.
- **Device Settings**—This item displays the current base address and interrupt request level (IRQ) information for the onboard parallel port.
- **Device Mode**—This setting enables alternate modes of operation for the parallel port. Usually the default setting works for all applications. The default is **STD Printer Mode**.
- **Change Settings**—This setting changes the base address and interrupt request level (IRQ) information for the onboard parallel port. The default value is **Auto**. Note that the options available vary based upon the **Device Mode** selected for the parallel port.

LabVIEW RT Setup Menu

Use this menu to configure boot options for LabVIEW RT if it is installed on the controller. If you are not using LabVIEW RT, you should leave these settings at default.

- **Boot Configuration**—This setting selects whether the controller should boot LabVIEW RT, LabVIEW RT Safe Mode, or an installed OS such as Windows 7. The default is **Use Switch Setting**.
- **Reset IP Address**—If the controller is deployed to a different subnet from which it was originally configured, or if the current IP address is invalid, use this switch to reset the IP address and other TCP/IP settings to their factory defaults during LabVIEW RT startup. The default is **Use Switch Setting**.

**Note**  
The settings below override the behavior of the switches shown in Figure 2-4. Refer to the **LabVIEW RT Configuration Switches** section for more information. To use the settings from the switches, select **Use Switch Setting** for each option.

- By default, the target will automatically attempt to connect to the network using DHCP. If the target is unable to initiate a DHCP connection, the target connects to the network with a link-local IP address of **169.254.x.x**.
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- **Disable Startup VI**—If the controller becomes inaccessible because of a startup VI, this switch can prevent VIs from automatically running at startup. The default is **Use Switch Setting**.

- **LabVIEW RT Configuration Overrides**—Use this setting to access the LabVIEW RT Configuration Overrides submenu. Refer to the LabVIEW RT Configuration Overrides Submenu section for more information.

**Current Hardware Switch Settings**

This submenu displays the current values of the LabVIEW RT configuration switches, indicating Boot Configuration, Reset IP Address, and Disable Startup VI switch status. For more information on these settings and the switches that control them, refer to the LabVIEW RT Configuration Switches section of this chapter.

**LabVIEW RT Configuration Overrides Submenu**

In order to minimize jitter when booting into LabVIEW Real-Time mode, the following features are automatically disabled. These features can be manually enabled. Refer to the CPU Configuration Submenu for specific details on what each feature enables.

- **CPU Hyper Threading**—The default is **Use RT Default**.
- **CPU C-States**—The default is **Use RT Default**.

**Boot Setup Menu**

Use this menu to configure settings related to the boot process and boot device priority.

- **Boot Settings Configuration**—Use this setting to access the Boot Settings Configuration Submenu. Refer to the Boot Settings Configuration Submenu section for more information.

- **PXE Drive Boot**—This setting specifies whether or not boot support is enabled for legacy mass storage devices, such as SCSI drives. When enabled, legacy mass storage controllers with boot support will be displayed in the Boot Option Priorities menu. The default value is **Enabled**.

- **PXE Network Boot**—This setting specifies whether or not the PXE network boot agent is enabled. When enabled, the Intel Boot Agent will be displayed in the Boot Option Priorities menu, allowing you to boot from a PXE server on the local subnet. Note that the Intel Boot Agent device names are preceded by **IBA GE Slot 00c9 v1310** in the Boot Option Priorities menu. The system must be restarted for this setting to take effect. The default value is **Disabled**.

- **Boot Option Priorities**—These settings specify the order in which the BIOS checks for bootable devices, including the local hard disk drive, removable devices such as USB flash disk drives or USB CD-ROM drives, or the PXE network boot agent. The BIOS will first attempt to boot from the device associated with **1st Boot Device**, followed by **2nd Boot Device**, and **3rd Boot Device**. If multiple boot devices are not present, the BIOS setup utility will not display all of these configuration options. To select a boot device, press <Enter> on the desired configuration option and select a boot device from the resulting menu. You can also disable certain boot devices by selecting **Disabled**.
Note Only one device of a given type will be shown in this list. If more than one device of the same type exists, use the Device BBS Priorities submenus to re-order the priority of devices of the same type.

The following submenus will be displayed if one or more bootable devices of the corresponding type is present:

- **Hard Drive BBS Priorities**—Use this setting to access the Hard Drive BBS Priorities submenu to re-order or disable bootable hard drive devices. Refer to the Hard Drive BBS Priorities Submenu section for more information.

- **CD/DVD ROM Drive BBS Priorities**—Use this setting to access the CD/DVD ROM Drive BBS Priorities submenu to re-order or disable bootable CD/DVD ROM drive devices. Refer to the CD/DVD ROM Drive BBS Priorities Submenu section for more information.

- **Floppy Drive BBS Priorities**—Use this setting to access the Floppy Drive BBS Priorities submenu to re-order or disable bootable floppy drive devices. Refer to the Floppy Drive BBS Priorities Submenu section for more information.

- **Network Device BBS Priorities**—Use this setting to access the Network Device BBS Priorities submenu to re-order or disable bootable network devices. Refer to the Network Device BBS Priorities Submenu section for more information.

### Boot Settings Configuration Submenu

Use this submenu to apply alternate configurations to boot settings. Normally, you do not need to modify these settings, as the factory default settings provide the most compatible and optimal configuration.

- **Setup Prompt Timeout**—This setting specifies the number of seconds the system will wait for a BIOS Setup menu keypress (the <Delete> key). The default value is 2.

- **Bootup NumLock State**—This setting specifies the power-on state of the keyboard NumLock setting. The default value is On.

### Hard Drive BBS Priorities Submenu

- **Boot Option #1, Boot Option #2, Boot Option #3**—These settings specify the boot priority of hard drive devices. The highest priority device is displayed on the main Boot Option Priorities list. Optionally, each device can also be Disabled if the device should never be used as a boot device.

### CD/DVD ROM Drive BBS Priorities Submenu

- **Boot Option #1, Boot Option #2, Boot Option #3**—These settings specify the boot priority of CD/DVD ROM drive devices. The highest priority device is displayed on the main Boot Option Priorities list. Optionally, each device can also be Disabled if the device should never be used as a boot device.
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Floppy Drive BBS Priorities Submenu

- **Boot Option #1, Boot Option #2, Boot Option #3**—These settings specify the boot priority of floppy drive devices. The highest priority device is displayed on the main **Boot Option Priorities** list. Optionally, each device can also be **Disabled** if the device should never be used as a boot device.

Network Device BBS Priorities Submenu

- **Boot Option #1, Boot Option #2, Boot Option #3**—These settings specify the boot priority of network devices. The highest priority device is displayed on the main **Boot Option Priorities** list. Optionally, each device can also be **Disabled** if the device should never be used as a boot device.

Security Menu

Use this menu to enable BIOS security options.

- **Administrator Password**—This setting specifies a password that must be entered to access the BIOS Setup Utility. If only the Administrator’s password is set, then this only limits access to the BIOS setup program and is only asked for when entering the BIOS setup program. By default, no password is specified.

- **User Password**—This setting specifies a password that must be entered to access the BIOS Setup Utility or to boot the system. If only the User’s password is set, then this is a power on password and must be entered to boot or enter the BIOS setup program. In the BIOS setup program, the User will have Administrator rights. By default, no password is specified.

Save & Exit Menu

The **Save & Exit** setup menu includes all available options for exiting, saving, and loading the BIOS default configuration. As an alternative to this screen, press `<F9>` to load optimal BIOS default settings and `<F10>` to save changes and exit setup.

The **Exit** setup menu includes the following settings:

- **Save Changes and Reset**—Any changes made to BIOS settings are stored in NVRAM. The setup program then exits and reboots the controller. The `<F10>` key can also be used to select this option.

- **Discard Changes and Reset**—Any changes made to BIOS settings during this session of the BIOS setup program are discarded. The setup program then exits and reboots the controller. The `<Esc>` key can also be used to select this option.

- **Save Changes**—Changes made to BIOS settings during this session are committed to NVRAM. The setup program remains active, allowing further changes.

- **Discard Changes**—Any changes made to BIOS settings during this session of the BIOS setup program are discarded. The BIOS setup continues to be active.

- **Restore Factory Defaults**—This option restores all BIOS settings to the factory default. This option is useful if the controller exhibits unpredictable behavior due to an incorrect or
inappropriate BIOS setting. Notice that any nondefault settings such as boot order, passwords, and so on, are also restored to their factory defaults. The <F9> key can also be used to select this option.

- **Save As User Defaults**—This option saves a copy of the current BIOS settings as the User Defaults. This option is useful for preserving custom BIOS setup configurations.
- **Restore User Defaults**—This option restores all BIOS settings to the user defaults. This option is useful for restoring previously preserved custom BIOS setup configurations.
- **Boot Override**—This option lists all possible bootable devices and allows the user to override the **Boot Option Priorities** list for the current boot. If no changes have been made to the BIOS setup options, the system will continue booting to the selected device without first rebooting. If BIOS setup options have been changed and saved, a reboot will be required and the boot override selection will not be valid.

**BIOS Diagnostic Utilities**

You can test the hard drive and memory of your controller with the included BIOS diagnostic utilities.

**Accessing BIOS Diagnostic Utilities**

Complete the following steps to start the BIOS Diagnostic Utility.

1. Power on or reboot your controller.
2. When the message **<F2> to run diagnostics** appears, press the <F2> key. The first diagnostic utility loads after a short delay.

**Hard Drive Diagnostic Utility**

The hard drive is tested first upon entry into the BIOS Diagnostic Utilities. A quick test is performed initially, and a more comprehensive test is performed second. The user may abort and skip any test by pressing the <Esc> key at any time during that test. After both tests have finished or been skipped, the user is presented with the testing results. If both tests have succeeded or been skipped, **Press any key to continue** is displayed. In order to continue with testing, user interaction is required to press a key on the keyboard.

**Note** If either hard drive test fails, the controller is not permitted to boot, and the user is instructed to turn off the controller and replace the hard drive.

**Memory Diagnostic Utility**

The memory diagnostic utility is started immediately after the user presses a key to exit the hard drive diagnostic utility. The user may abort and skip the memory test by pressing the <Esc> key at any time during this test. After the memory utility has finished or been skipped, the user is presented with the testing result. If the memory test was successful or skipped, **Press any key to continue** is displayed. In order to continue to boot the controller, user interaction is required to press a key on the keyboard.
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Note  If the memory test fails, the controller is not permitted to boot, and the user is instructed to turn off the controller and replace the memory.

System CMOS

The NI PXIe-8135 contains memory backed up by a battery to store BIOS configuration information.

Complete the following steps to clear the CMOS contents:
1.  Power off the chassis.
2.  Remove the controller from the chassis.
3.  Press the push-button switch, as shown in Figure 2-3.
4.  Wait ten seconds.
5.  Reinstall the controller in the chassis.

Figure 2-3.  Clearing the CMOS Contents

1  Push-Button Switch SW2
LabVIEW RT Installation

This section explains software installation and switch configuration for LabVIEW RT on your PXI Express controller.

LabVIEW RT Software Installation

The following section describes the necessary steps to get your PXI Express embedded controller setup to run LabVIEW Real-Time. In this section you will configure the boot mode of the controller, verify or change IP settings, and install LabVIEW Real-Time software.

Complete the following steps to install the LabVIEW RT software.

1. Boot the NI PXI Express embedded controller into the real-time operating system. Refer to the LabVIEW RT Configuration Switches section or the LabVIEW RT Setup Menu section in this manual to configure the controller for booting into LabVIEW RT.

The PXI Express controller will automatically boot into LabVIEW RT Safe Mode when no software is installed. LabVIEW RT Safe Mode loads with the basic real-time operating system and will automatically attempt to connect to the network using DHCP. If DHCP is not available, it will then connect to the network with a link-local IP address.

Tip: You can connect a monitor to the desktop PC to display startup messages such as the IP address and MAC address.

2. Open Measurement & Automation Explorer (MAX) on another computer in the same subnet and expand the Remote Systems branch. MAX lists the PXI Express controller as the model name of the controller followed by the MAC address (for example, NI-PXIe-8135 00802f108562).

Note: The other computer must have LabVIEW, LabVIEW RT, and any desired drivers installed.

Tip: Record the PXI Express controller MAC address, located on the side of the controller, for use in identifying the controller. The label also can be removed and placed on the front of the controller for easier access.

3. Click on the appropriate PXI Express controller entry to access the Network Settings tab in the right pane view.

4. (Optional) Enter a name for the RT target in the Name text box.

5. (Optional) Set the network configuration options of the RT target in the IP Settings section and click the Apply button.

For information about configuring network settings, refer to the Configuring Network Settings book, accessible by browsing to MAX Remote Systems Help»LabVIEW Real-Time Target Configuration»Configuring Network Settings from the Contents tab of MAX Help.
Note When any IP or identification settings are changed, you will be prompted to reboot the controller for the changes to take effect. Click Yes to automatically reboot the RT target. You may also reboot the controller by right-clicking on the target name under Remote Systems and selecting Reboot.

After rebooting the PXI Express controller it will appear in the Remote Systems category with the assigned name.

6. Expand the PXI Express controller view in the Remote Systems branch and select Software.
7. Click the Add/Remove Software button in the toolbar to launch the LabVIEW Real-Time Software Wizard.
8. Install the LabVIEW Real-Time software and device drivers that you require on the RT target. Refer to the NI Web site at ni.com/info and enter the Info Code etspc for the latest information about supported software.

After installation of the software the controller will automatically reboot and you will now be able to program it using LabVIEW Real-Time.

Note Refer to the RT Getting Started Guide available on your host computer for more information about setting up your RT target.

LabVIEW RT Configuration Switches
Use the LabVIEW RT configuration switches to configure LabVIEW RT if it is installed on the controller. If you are not using LabVIEW RT, these switches should remain in the OFF position. The controller reads these switches only after a system reset.

The NI PXIe-8135 controller includes the following LabVIEW RT configuration switches:
- Switch 1—Boot LabVIEW RT: Set this switch to ON to boot LabVIEW RT.
- Switch 2—Boot Safe Mode: Set this switch to ON to boot LabVIEW RT into safe mode to reconfigure TCP/IP settings and to download or update software from a host computer. This switch overrides the behavior of Switch 1. Booting the controller into safe mode does not start the embedded LabVIEW RT engine. After changing the settings or software, reboot the controller with this switch OFF to resume normal operation.
- Switch 3—Disable Startup VI: Set this switch to ON to prevent VIs from automatically running at startup if the controller becomes inaccessible because of a startup VI.
- Switch 4—Reset IP Address: Set this switch to ON to reset the IP address and other TCP/IP settings to their factory defaults. Use this switch if moving the controller to a different subnet or if the current TCP/IP settings are valid.

Note By default, the target will automatically attempt to connect to the network using DHCP. If the target is unable to initiate a DHCP connection, the target connects to the network with a link-local IP address or 169.254.x.x.
Figure 2-4 shows the location of the LabVIEW RT configuration switches. The switches are shown in the OFF position.

**Figure 2-4. LabVIEW RT Configuration Switches**

<p>| | |</p>
<table>
<thead>
<tr>
<th></th>
<th></th>
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</thead>
<tbody>
<tr>
<td>1</td>
<td>Switch 1—Boot LabVIEW RT</td>
</tr>
<tr>
<td>2</td>
<td>Switch 2—Boot Safe Mode</td>
</tr>
<tr>
<td>3</td>
<td>Switch 3—Disable Startup VI</td>
</tr>
<tr>
<td>4</td>
<td>Switch 4—Reset IP Address</td>
</tr>
</tbody>
</table>

**Drivers and Software**

Your hard drive includes a directory called `images` in its root that contains software and soft copies of manuals for the peripherals. The directory structure under the `images` directory is logically organized into several levels.

In the `images` directory, you will find a `manuals` directory, an `os` directory, and a `drivers` directory.

The `manuals` directory contains quick reference guides, technical reference manuals, and National Instruments software manuals, all in Adobe Acrobat format. To access any manual, change your directory to `c:\images\manuals` and list the contents of that directory.

The `os` directory contains a subdirectory corresponding to the operating system installed on your computer.

The `drivers` directory contains driver installers for the system peripherals. These files and directories are copied exactly from the manufacturer distribution disks, so the naming conventions vary from peripheral to peripheral.
Chapter 2  Installation and Configuration

PXI Express Features

PXI Express Trigger Connectivity
The SMB connector on the NI PXIe-8135 front panel can connect to or from any PXI Express backplane trigger line. A trigger allocation process is needed to prevent two resources from connecting to the same trigger line, resulting in the trigger being double-driven and possibly damaging the hardware. At the time of this manual’s publication, this software is not yet available for Windows. Contact National Instruments for more information.

PXI Express Chassis Configuration

The PXI Express Platform Services software installed on your controller and available on the National Instruments Driver DVD or PXI Platform Services CD included with your kit automatically identifies your PXI Express system components to generate a pxisys.ini and pxisys.ini file. You can configure your entire PXI Express system through Measurement & Automation Explorer (MAX), included with your controller. MAX creates the pxisys.ini and pxisys.ini file, which define your PXI Express system parameters. MAX also provides an interface to route and reserve triggers so dynamic routing, through drivers such as DAQmx, avoids double-driving and potentially damaging trigger lines. For more information about routing and reserving PXI Express triggers, refer to KnowledgeBase 3TJDOND8, Using PXI Timing and Triggering Functionality, at ni.com/support.

The configuration steps for single or multiple-chassis systems are the same.

PXI Express System Configuration

2. In the Configuration tree, expand Devices and Interfaces.
3. In the Devices and Interfaces tree, expand PXI System. Your PXI Express chassis is already identified and appears in the PXI System tree.
4. For each unidentified PXI Express chassis in the PXI System tree, right-click on the chassis and select the appropriate chassis model through the Identify As submenu. Further expanding the PXI System branch shows all devices in the system that NI-VISA can recognize.

The PXI Express specification allows for many combinations of PXI Express chassis and system modules. To assist system integrators, PXI Express chassis and system module manufacturers must document their products’ capabilities. PXI Express devices must provide a driver and/or .ini file for identification. For NI PXI Express chassis and controllers, these files are provided as part of the NI PXI Platform Services software included with your controller. System integrators, configuration utilities, and device drivers can use these .ini files.

The NI PXI Platform Services software uses the system module driver, chassis driver, and chassis.ini files to generate the PXI/PXI Express system description files (pxisys.ini
Device drivers and other utility software read the pxiesys.ini and pxisys.ini files to obtain system information. For detailed information about initialization files, refer to the PXI Express specification at www.pxisa.org.

Upgrading RAM

You can change the amount of installed RAM on the NI PXIe-8135 by upgrading the SO-DIMMs.

To upgrade the RAM, remove the NI PXIe-8135 from the PXI Express chassis. To optimize both memory capacity and system performance, use the same size and speed memory module in each of the two module slots. The use of different size modules in each slot is supported, but system performance will be slower than using two matched modules. However, two mismatched modules could result in better performance than using a single module.

National Instruments offers the following SO-DIMM for use with the NI PXIe-8135 controller.

- PC3-12800 (DDR3 1600) 4 GB, 256 MB ×64, CL 9, 1.18 in. max (NI part number 782341-4096)
- PC3-12800 (DDR3 1600) 8 GB, 512 MB ×64, CL 9, 1.18 in. max (NI part number 782341-8192)

Note National Instruments has tested and verified that the DDR3 SO-DIMMs we sell work with the NI PXIe-8135. We recommend you purchase your DDR3 SO-DIMM modules from National Instruments. Other off-the-shelf DDR3 SO-DIMM modules are not guaranteed to work properly.

When installing memory modules into the memory sockets, the lower socket must be populated first, followed by the upper socket. If a single memory module is used, it must be installed in the lower socket.

The NI PXIe-8135 removable hard drive variant has a single module slot that supports up to an 8 GB DDR3 SO-DIMM module.
NI PXIe-8135 controllers include two methods of restoring the original factory condition of your hard drive. Hard drive-based recovery stores a factory backup on a separate portion of your hard drive allowing you to restore your controller without additional media. The NI PXIe-8135 controller also ships with an OS Recovery CD that allows you to reinstall your operating system onto your hard drive through an external USB CD/DVD-ROM. For more information on these tools, refer to KnowledgeBase 2ZKC02OK, *Hard Drive Recovery and OS Installation for PXI and VXI Controllers*, at ni.com/support.

**Note** The hard drive recovery hot key is <F4>. To access the hard drive-based recovery tool, press and hold <F4> when video first appears during the boot process.

If you need to recover your factory-installed operating system from a CD, you can use the included OS re-installation CD with an external USB CD/DVD-ROM drive. Boot the PXI Express controller using the OS re-installation CD to recover the OS. You also may need to reinstall other software after using the CD to recover the OS.

**Note** Recovering the OS erases the contents of your hard disk. Back up any files you want to keep.
Installing an OS

NI PXIe-8135 controllers include a preinstalled OS. In some cases, you may want to install a different OS. When doing so, consider the following guidelines.

Installing from a USB CD/DVD-ROM

The NI PXIe-8135 supports the installation of Windows 7 or Windows XP from a USB CD/DVD-ROM. As an alternative to a USB CD/DVD-ROM drive, you can use an external SCSI CD-ROM with a PXI-SCSI adapter.

Note For additional assistance with installing or changing an operating system, refer to KnowledgeBase 2ZKC02OK, Hard Drive Recovery and OS Installation for PXI and VXI Controllers, at ni.com/support.

ExpressCard

This section provides information on the installation and removal of ExpressCard™ modules.

Installing an ExpressCard

You can install an ExpressCard module while the NI PXIe-8135 is running. The NI PXIe-8135 will automatically detect the card. ExpressCards are generally marked with a symbol or a label to indicate which end to insert into the slot. The cards are keyed to prevent incorrect insertion.

To install an ExpressCard, complete the following steps.

1. Hold the card so the top side is facing left.
2. Insert the card until it is completely seated in its connector. The connector has an automatic eject mechanism. If you insert the card and it is ejected, simply re-insert the card until it is seated.

If you encounter too much resistance, do not force the card. Check the card orientation and try again.

The NI PXIe-8135 will automatically recognize the ExpressCard and load the appropriate driver(s). Third-party cards may require that you install additional drivers. Contact your ExpressCard vendor for more information.

Removing an ExpressCard

To remove the ExpressCard module push in the module and then release to eject the card. Slide the card out of the slot.

Caution To avoid data loss and other potential issues, stop communication with your ExpressCard device before removing it from the NI PXIe-8135. In Windows, use the Safely Remove Hardware tool to safely stop the ExpressCard.
Chapter 2  Installation and Configuration

Removable Hard Drive

This section provides information on the installation and removal of the removable hard drive.

⚠️ Caution  The removable hard drive must be installed before powering on the NI PXIe-8135 and should not be removed during operation.

Installing the Removable Hard Drive

To install the removable hard drive, complete the following steps:

1. Hold the removable hard drive so that the top side is facing right, as shown in Figure 2-6.
2. Insert the removable hard drive so that it is completely seated in its connector. The insertion resistance will increase for the final connector mate.
3. If the removable hard drive does not easily insert, do not force the drive. Check the alignment and try again. The removable hard drive may not be flush with the front of the NI PXIe-8135 when fully inserted.
4. Tighten the thumb screws. If the thumb screws do not thread, the removable hard drive may not be fully inserted. Try removing and completely inserting the removable hard drive.

Figure 2-6. Installing the Removable Hard Drive in an NI PXIe-8135 Controller

![Figure 2-6. Installing the Removable Hard Drive in an NI PXIe-8135 Controller](image-url)
Removing the Removable Hard Drive

To remove the removable hard drive, complete the following steps:

1. Power off the chassis.
2. Loosen the thumb screws.
3. Unseat the removable hard drive from the connector and remove it from the slot.

Store the hard drive in the original antistatic packaging when not in use to avoid damage.
## I/O Information

### Front Panel Connectors

Table 3-1 lists various peripherals and their corresponding NI PXIe-8135 external connectors, bus interfaces, and functions.

#### Table 3-1. NI PXIe-8135 Peripherals Overview

<table>
<thead>
<tr>
<th>Peripheral</th>
<th>External Connector</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Video</td>
<td>DisplayPort (2 connectors)</td>
<td>ATI Radeon E4690 Embedded GPU</td>
</tr>
<tr>
<td>Serial</td>
<td>COM1 (9-pin DSUB)</td>
<td>16550 RS-232 serial port</td>
</tr>
<tr>
<td>Ethernet Port 1</td>
<td>LAN (RJ45, dual stacked)</td>
<td>10/100/1000 Ethernet Intel 82579 WOL capable</td>
</tr>
<tr>
<td>Ethernet Port 2</td>
<td>LAN (RJ45, dual stacked)</td>
<td>10/100/1000 Ethernet Intel 82574 Not WOL capable</td>
</tr>
<tr>
<td>Parallel</td>
<td>Parallel Port (36-pin champ)</td>
<td>IEEE 1284</td>
</tr>
<tr>
<td>USB 2.0</td>
<td>USB 4-pin Series A stacked receptacle (4 ports)</td>
<td>USB 2.0 capable</td>
</tr>
<tr>
<td>USB 3.0</td>
<td>USB 9-pin Series A stacked receptacle (2 ports)</td>
<td>USB 3.0 and USB 2.0 capable</td>
</tr>
<tr>
<td>PXI Express trigger</td>
<td>Trigger (SMB)</td>
<td>Routing PXI Express triggers to or from the backplane trigger bus</td>
</tr>
<tr>
<td>GPIB device</td>
<td>GPIB (25-pin Micro D)</td>
<td>General-Purpose Interface Bus, IEEE 488.2</td>
</tr>
</tbody>
</table>

**ExpressCard Variant**

| ExpressCard/34 module | ExpressCard/34 slot | ExpressCard/34 expansion |
Chapter 3  I/O Information

Table 3-1. NI PXIe-8135 Peripherals Overview (Continued)

<table>
<thead>
<tr>
<th>Peripheral</th>
<th>External Connector</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Removable Hard Drive</td>
<td>Removable HDD</td>
<td>Removable Hard Disk Drive</td>
</tr>
</tbody>
</table>

Front Panel

Figures 3-1 and 3-2 show the front panel layout and dimensions of the NI PXIe-8135. Dimensions are in inches [millimeters].

Figure 3-1. NI PXIe-8135 Front Panel Layout and Dimensions (ExpressCard Variant)
Figure 3-2. NI PXIe-8135 Front Panel Layout and Dimensions
(Removable Hard Drive Variant)
DisplayPort

Figure 3-3 shows the location and pinouts for the DisplayPort connectors on the NI PXIe-8135. Table 3-2 lists and describes the DisplayPort connector signals.

**Figure 3-3. DisplayPort Connector Location and Pinout**

<table>
<thead>
<tr>
<th>Pin</th>
<th>Signal Name</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>ML_Lane0(p)</td>
</tr>
<tr>
<td>2</td>
<td>GND</td>
</tr>
<tr>
<td>3</td>
<td>ML_Lane0(n)</td>
</tr>
<tr>
<td>4</td>
<td>ML_Lane1(p)</td>
</tr>
<tr>
<td>5</td>
<td>GND</td>
</tr>
<tr>
<td>6</td>
<td>ML_Lane1(n)</td>
</tr>
<tr>
<td>7</td>
<td>ML_Lane2(p)</td>
</tr>
<tr>
<td>8</td>
<td>GND</td>
</tr>
<tr>
<td>9</td>
<td>ML_Lane2(n)</td>
</tr>
<tr>
<td>10</td>
<td>ML_Lane3(p)</td>
</tr>
<tr>
<td>11</td>
<td>GND</td>
</tr>
<tr>
<td>12</td>
<td>ML_Lane3(n)</td>
</tr>
<tr>
<td>13</td>
<td>CONFIG1</td>
</tr>
</tbody>
</table>
**Table 3-2. DisplayPort Connector Signals (Continued)**

<table>
<thead>
<tr>
<th>Pin</th>
<th>Signal Name</th>
</tr>
</thead>
<tbody>
<tr>
<td>14</td>
<td>CONFIG2</td>
</tr>
<tr>
<td>15</td>
<td>AUX CH (p)</td>
</tr>
<tr>
<td>16</td>
<td>GND</td>
</tr>
<tr>
<td>17</td>
<td>AUX CH (n)</td>
</tr>
<tr>
<td>18</td>
<td>Hot Plug Detect</td>
</tr>
<tr>
<td>19</td>
<td>Return</td>
</tr>
<tr>
<td>20</td>
<td>DP_PWR</td>
</tr>
</tbody>
</table>

**COM1**

Figure 3-4 shows the location and pinouts for the COM1 connector on the NI PXIe-8135. Table 3-3 lists and describes the COM1 connector signal.

AMP manufactures a serial port mating connector, part number 745491-5.

**Figure 3-4. COM1 Connector Location and Pinout**
Chapter 3  I/O Information

Table 3-3. COM1 Connector Signals

<table>
<thead>
<tr>
<th>Pin</th>
<th>Signal Name</th>
<th>Signal Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>DCD#</td>
<td>Data Carrier Detect</td>
</tr>
<tr>
<td>2</td>
<td>RXD#</td>
<td>Receive Data</td>
</tr>
<tr>
<td>3</td>
<td>TXD#</td>
<td>Transmit Data</td>
</tr>
<tr>
<td>4</td>
<td>DTR#</td>
<td>Data Terminal Ready</td>
</tr>
<tr>
<td>5</td>
<td>GND</td>
<td>Ground</td>
</tr>
<tr>
<td>6</td>
<td>DSR#</td>
<td>Data Set Ready</td>
</tr>
<tr>
<td>7</td>
<td>RTS#</td>
<td>Ready to Send</td>
</tr>
<tr>
<td>8</td>
<td>CTS#</td>
<td>Clear to Send</td>
</tr>
<tr>
<td>9</td>
<td>RI#</td>
<td>Ring Indicator</td>
</tr>
</tbody>
</table>

Note: The pound symbol (#) indicates an active low signal.

Ethernet

Figure 3-5 shows the location and pinouts for the dual stacked Ethernet connector on the NI PXIe-8135. Table 3-4 lists and describes the Ethernet connector signals.

AMP manufactures a mating connector, part number 554739-1.

Figure 3-5. Ethernet Connector Location and Pinout
The Ethernet controllers can perform an automatic crossover, thus eliminating the need for crossover cables.

<table>
<thead>
<tr>
<th>Pin</th>
<th>Fast Ethernet</th>
<th>Gigabit Ethernet</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>TX+</td>
<td>TX_A+</td>
</tr>
<tr>
<td>2</td>
<td>TX-</td>
<td>TX_A-</td>
</tr>
<tr>
<td>3</td>
<td>RX+</td>
<td>RX_B+</td>
</tr>
<tr>
<td>4</td>
<td>NC</td>
<td>TX_C+</td>
</tr>
<tr>
<td>5</td>
<td>NC</td>
<td>TX_C-</td>
</tr>
<tr>
<td>6</td>
<td>RX-</td>
<td>RX_B-</td>
</tr>
<tr>
<td>7</td>
<td>NC</td>
<td>RX_D+</td>
</tr>
<tr>
<td>8</td>
<td>NC</td>
<td>RX_D-</td>
</tr>
</tbody>
</table>

Table 3-4. Ethernet Connector Signals

Table 3-5. 10/100/1000 LAN Connector LED States

<table>
<thead>
<tr>
<th>LED</th>
<th>Color</th>
<th>LED State</th>
<th>Condition</th>
</tr>
</thead>
<tbody>
<tr>
<td>ACT/LINK</td>
<td>Green</td>
<td>Off</td>
<td>LAN link is not established.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>On (steady state)</td>
<td>LAN link is established.</td>
</tr>
<tr>
<td></td>
<td></td>
<td>On (brighter and pulsing)</td>
<td>The controller is communicating with another computer on the LAN.</td>
</tr>
<tr>
<td>10/100/1000</td>
<td>(None)</td>
<td>Off</td>
<td>10 Mbit/sec data rate is selected.</td>
</tr>
<tr>
<td></td>
<td>Green</td>
<td>On</td>
<td>100 Mbit/sec data rate is selected.</td>
</tr>
<tr>
<td></td>
<td>Amber</td>
<td>On</td>
<td>1000 Mbit/sec data rate is selected.</td>
</tr>
</tbody>
</table>
Parallel Port

Figure 3-6 shows the location and pinouts for the IEEE 1284 (parallel) connector on the NI PXIe-8135. Table 3-6 lists and describes the IEEE 1284 connector signals.

Parallel port adapter cables are available from National Instruments, part number 777169-01.

![Parallel Port Connector Location and Pinout](image)

**Figure 3-6.** Parallel Port Connector Location and Pinout

<table>
<thead>
<tr>
<th>Pin</th>
<th>Default Configuration (LPT)</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>BUSY</td>
</tr>
<tr>
<td>2</td>
<td>SLCT</td>
</tr>
<tr>
<td>3</td>
<td>ACK#</td>
</tr>
<tr>
<td>4</td>
<td>FAULT/#(ERROR#)</td>
</tr>
<tr>
<td>5</td>
<td>PAPEREND</td>
</tr>
<tr>
<td>6</td>
<td>PD0</td>
</tr>
<tr>
<td>7</td>
<td>PD1</td>
</tr>
<tr>
<td>8</td>
<td>PD 2</td>
</tr>
<tr>
<td>9</td>
<td>PD3</td>
</tr>
<tr>
<td>10</td>
<td>PD4</td>
</tr>
<tr>
<td>11</td>
<td>PD5</td>
</tr>
</tbody>
</table>

**Table 3-6.** Parallel Port Connector Signals

Signal Name    Signal Description
---            -------------------
BUSY          Device Busy
SLCT          Select
ACK#          Acknowledge
FAULT/#(ERROR#)  Fault
PAPEREND     Paper End
PD0           Data Bit 0
PD1           Data Bit 1
PD 2          Data Bit 2
PD3           Data Bit 3
PD4           Data Bit 4
PD5           Data Bit 5
Table 3-6. Parallel Port Connector Signals (Continued)

<table>
<thead>
<tr>
<th>Pin</th>
<th>Default Configuration (LPT)</th>
<th>Signal Name</th>
<th>Signal Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>12</td>
<td></td>
<td>PD6</td>
<td>Data Bit 6</td>
</tr>
<tr>
<td>13</td>
<td></td>
<td>PD7</td>
<td>Data Bit 7</td>
</tr>
<tr>
<td>14</td>
<td></td>
<td>INIT#</td>
<td>Initialize Printer</td>
</tr>
<tr>
<td>15</td>
<td></td>
<td>STROBE#</td>
<td>Strobe</td>
</tr>
<tr>
<td>16</td>
<td></td>
<td>SLCTIN#</td>
<td>Select Input</td>
</tr>
<tr>
<td>17</td>
<td></td>
<td>AUTOFD#</td>
<td>Auto Line Feed</td>
</tr>
<tr>
<td>18</td>
<td></td>
<td>+5V</td>
<td>+5 V</td>
</tr>
<tr>
<td>19 to 35</td>
<td></td>
<td>GND</td>
<td>Ground</td>
</tr>
<tr>
<td>36</td>
<td></td>
<td>NC</td>
<td>Not Connected</td>
</tr>
</tbody>
</table>

**Note:** The pound symbol (#) indicates an active low signal.

**Universal Serial Bus**

Figure 3-7 shows the location and pinouts for the Universal Serial Bus (USB) connectors on the NI PXIe-8135. Each controller has 4 USB ports on the front panel. Table 3-7 lists and describes the USB connector signals.

**Figure 3-7. USB Connector Location and Pinout**
### Table 3-7. USB 2.0 Connector Signals

<table>
<thead>
<tr>
<th>Pin</th>
<th>Signal Name</th>
<th>Signal Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>VCC</td>
<td>Cable Power (+5 V)</td>
</tr>
<tr>
<td>2</td>
<td>-Data</td>
<td>USB Data -</td>
</tr>
<tr>
<td>3</td>
<td>+Data</td>
<td>USB Data +</td>
</tr>
<tr>
<td>4</td>
<td>GND</td>
<td>Ground</td>
</tr>
</tbody>
</table>

### Table 3-8. USB 3.0 Connector Signals

<table>
<thead>
<tr>
<th>Pin</th>
<th>Signal Name</th>
<th>Signal Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>VCC</td>
<td>Cable Power (+5 V)</td>
</tr>
<tr>
<td>2</td>
<td>-Data</td>
<td>USB Data -</td>
</tr>
<tr>
<td>3</td>
<td>+Data</td>
<td>USB Data +</td>
</tr>
<tr>
<td>4</td>
<td>GND</td>
<td>Ground</td>
</tr>
<tr>
<td>5</td>
<td>StdA_SSRX-</td>
<td>USB Data Receive-</td>
</tr>
<tr>
<td>6</td>
<td>StdA_SSRX+</td>
<td>USB Data Receive+</td>
</tr>
<tr>
<td>7</td>
<td>GND_DRAIN</td>
<td>Ground</td>
</tr>
<tr>
<td>8</td>
<td>StdA_SSTX-</td>
<td>USB Data Transmit-</td>
</tr>
<tr>
<td>9</td>
<td>StdA_SSTX+</td>
<td>USB Data Transmit+</td>
</tr>
</tbody>
</table>
Trigger

The TRIG connector is the software-controlled trigger connection for routing PXI Express triggers to or from the backplane trigger bus.

Figure 3-8 shows the TRIG connector location on the NI PXIe-8135. Table 3-9 lists and describes the trigger connector signals.

**Figure 3-8. TRIG Connector Location and Pinout**

![TRIG Connector Location and Pinout](image)

**Table 3-9. TRIG Connector Signals**

<table>
<thead>
<tr>
<th>Pin</th>
<th>Signal Name</th>
<th>Signal Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>TRIG</td>
<td>Trigger</td>
</tr>
<tr>
<td>2 (Shield)</td>
<td>GND</td>
<td>Ground</td>
</tr>
</tbody>
</table>
GPIB (IEEE 488.2)

Figure 3-9 shows the location and pinouts for the GPIB connector on the NI PXIe-8135. Table 3-10 lists and describes the GPIB connector signals.

ITT Canon manufactures a GPIB mating connector, part number MDSM-25SC-Z11-V51.

Figure 3-9. GPIB Connector Location and Pinout

Table 3-10. GPIB Connector Signals

<table>
<thead>
<tr>
<th>Pin</th>
<th>Signal Name</th>
<th>Signal Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>DIO1#</td>
<td>Data Bit 1</td>
</tr>
<tr>
<td>2</td>
<td>DIO2#</td>
<td>Data Bit 2</td>
</tr>
<tr>
<td>3</td>
<td>DIO3#</td>
<td>Data Bit 3</td>
</tr>
<tr>
<td>4</td>
<td>DIO4#</td>
<td>Data Bit 4</td>
</tr>
<tr>
<td>5</td>
<td>EOI#</td>
<td>End or Identify</td>
</tr>
<tr>
<td>6</td>
<td>DAV#</td>
<td>Data Valid</td>
</tr>
<tr>
<td>7</td>
<td>NRFD#</td>
<td>Not Ready for Data</td>
</tr>
<tr>
<td>8</td>
<td>NDAC#</td>
<td>Not Data Accepted</td>
</tr>
<tr>
<td>9</td>
<td>IFC#</td>
<td>Interface Clear</td>
</tr>
<tr>
<td>10</td>
<td>SRQ#</td>
<td>Service Request</td>
</tr>
<tr>
<td>11</td>
<td>ATN#</td>
<td>Attention</td>
</tr>
<tr>
<td>12</td>
<td>SHIELD</td>
<td>Chassis ground</td>
</tr>
</tbody>
</table>
The NI PXIe-8135 controller can be equipped with an optional ExpressCard/34 slot on the front panel, providing I/O expansion and options for removable storage.

Figure 3-10 shows the location and pinouts for the ExpressCard/34 slot on the NI PXIe-8135. Table 3-11 lists and describes the ExpressCard connector signals.

### ExpressCard/34 Slot (Optional)

<table>
<thead>
<tr>
<th>Pin</th>
<th>Signal Name</th>
<th>Signal Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>13</td>
<td>DIO5#</td>
<td>Data Bit 5</td>
</tr>
<tr>
<td>14</td>
<td>DIO6#</td>
<td>Data Bit 6</td>
</tr>
<tr>
<td>15</td>
<td>DIO7#</td>
<td>Data Bit 7</td>
</tr>
<tr>
<td>16</td>
<td>DIO8#</td>
<td>Data Bit 8</td>
</tr>
<tr>
<td>17</td>
<td>REN#</td>
<td>Remote Enable</td>
</tr>
<tr>
<td>18 to 25</td>
<td>GND</td>
<td>Logic Ground</td>
</tr>
</tbody>
</table>

*Note: The pound symbol (#) indicates an active low signal.*

Table 3-10. GPIB Connector Signals (Continued)
Table 3-11. ExpressCard Connector Signals

<table>
<thead>
<tr>
<th>Pin</th>
<th>Signal Name</th>
<th>Signal Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>GND</td>
<td>Ground</td>
</tr>
<tr>
<td>2</td>
<td>USB Data -</td>
<td>USB Data -</td>
</tr>
<tr>
<td>3</td>
<td>USB Data +</td>
<td>USB Data +</td>
</tr>
<tr>
<td>4</td>
<td>CPUSB#</td>
<td>USB Presence</td>
</tr>
<tr>
<td>5</td>
<td>RESERVED</td>
<td>Reserved by spec for future use</td>
</tr>
<tr>
<td>6</td>
<td>RESERVED</td>
<td>Reserved by spec for future use</td>
</tr>
<tr>
<td>7</td>
<td>SMBCLK</td>
<td>SMBus Clock</td>
</tr>
<tr>
<td>8</td>
<td>SMBDATA</td>
<td>SMBus Data</td>
</tr>
<tr>
<td>9</td>
<td>+1.5V</td>
<td>Power</td>
</tr>
<tr>
<td>10</td>
<td>+1.5V</td>
<td>Power</td>
</tr>
<tr>
<td>11</td>
<td>WAKE#</td>
<td>PE Wake</td>
</tr>
<tr>
<td>12</td>
<td>+3.3V AUX</td>
<td>Power</td>
</tr>
<tr>
<td>13</td>
<td>PERST#</td>
<td>PE Reset</td>
</tr>
<tr>
<td>14</td>
<td>+3.3V</td>
<td>Power</td>
</tr>
<tr>
<td>15</td>
<td>+3.3V</td>
<td>Power</td>
</tr>
<tr>
<td>16</td>
<td>CLKREQ#</td>
<td>Clock Request</td>
</tr>
<tr>
<td>17</td>
<td>CPPE#</td>
<td>PE Presence</td>
</tr>
<tr>
<td>18</td>
<td>REFCLK-</td>
<td>Reference Clock -</td>
</tr>
<tr>
<td>19</td>
<td>REFCLK+</td>
<td>Reference Clock +</td>
</tr>
<tr>
<td>20</td>
<td>GND</td>
<td>Ground</td>
</tr>
<tr>
<td>21</td>
<td>PE Data Receive -</td>
<td></td>
</tr>
<tr>
<td>22</td>
<td>PE Data Receive +</td>
<td></td>
</tr>
<tr>
<td>23</td>
<td>GND</td>
<td>Ground</td>
</tr>
<tr>
<td>24</td>
<td>PE Data Transmit -</td>
<td></td>
</tr>
</tbody>
</table>
Removable Hard Drive (Optional)

The NI PXIe-8135 controller can be equipped with an optional removable hard drive on the front panel, providing an option for removable storage.

Figure 3-11 shows the location and pinouts for the removable hard drive on the NI PXIe-8135. Table 3-11 lists and describes the removable hard drive connector signals.

Table 3-11. Removable Hard Drive Connector Signals (Continued)

<table>
<thead>
<tr>
<th>Pin</th>
<th>Signal Name</th>
<th>Signal Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>25</td>
<td>PETp0</td>
<td>PE Data Transmit +</td>
</tr>
<tr>
<td>26</td>
<td>GND</td>
<td>Ground</td>
</tr>
</tbody>
</table>

*Note: The pound symbol (#) indicates an active low signal.*

Table 3-12. Removable Hard Drive Connector Signals

<table>
<thead>
<tr>
<th>Pin</th>
<th>Signal Name</th>
<th>Signal Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>S1</td>
<td>GND</td>
<td>Ground</td>
</tr>
<tr>
<td>S2</td>
<td>A+</td>
<td>SATA Transmit</td>
</tr>
<tr>
<td>S3</td>
<td>A-</td>
<td>SATA Transmit</td>
</tr>
<tr>
<td>S4</td>
<td>GND</td>
<td>Ground</td>
</tr>
<tr>
<td>S5</td>
<td>B+</td>
<td>SATA Receive</td>
</tr>
<tr>
<td>S6</td>
<td>B-</td>
<td>SATA Receive</td>
</tr>
</tbody>
</table>
### Table 3-12. Removable Hard Drive Connector Signals (Continued)

<table>
<thead>
<tr>
<th>Pin</th>
<th>Signal Name</th>
<th>Signal Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>S7</td>
<td>GND</td>
<td>Ground</td>
</tr>
<tr>
<td>P1</td>
<td>3.3 V</td>
<td>Power</td>
</tr>
<tr>
<td>P2</td>
<td>3.3 V</td>
<td>Power</td>
</tr>
<tr>
<td>P3</td>
<td>3.3 V</td>
<td>Power</td>
</tr>
<tr>
<td>P4</td>
<td>GND</td>
<td>Ground</td>
</tr>
<tr>
<td>P5</td>
<td>GND</td>
<td>Ground</td>
</tr>
<tr>
<td>P6</td>
<td>GND</td>
<td>Ground</td>
</tr>
<tr>
<td>P7</td>
<td>5 V</td>
<td>Power</td>
</tr>
<tr>
<td>P8</td>
<td>5 V</td>
<td>Power</td>
</tr>
<tr>
<td>P9</td>
<td>5 V</td>
<td>Power</td>
</tr>
<tr>
<td>P10</td>
<td>GND</td>
<td>Ground</td>
</tr>
<tr>
<td>P11</td>
<td>GND/Optional</td>
<td>Ground/Act/Staggerd Spinup</td>
</tr>
<tr>
<td>P12</td>
<td>GND</td>
<td>Ground</td>
</tr>
<tr>
<td>P13</td>
<td>NC</td>
<td>No Connect</td>
</tr>
<tr>
<td>P14</td>
<td>NC</td>
<td>No Connect</td>
</tr>
<tr>
<td>P15</td>
<td>NC</td>
<td>No Connect</td>
</tr>
</tbody>
</table>
Front Panel Features

The NI PXIe-8135 has the following front-panel features:

- A system reset pushbutton (press the button to generate a reset to the controller)
- Two front panel LEDs that show PC status
  - The **PWR OK/FAULT** LED indicates the status of the controller. The LED will indicate one of the following states:
    - Green ON steady—PXI Express and onboard power is on and within regulation limits.
    - Green BLINKING—The controller has entered the soft off state and is safe to power down.
    - OFF—The controller is powered off.
    - Red BLINKING—The controller detected a power rail fault when trying to boot.
    - Red Solid—The controller detected a thermal fault and has shut down to protect the system.
  - The **DRIVE** LED indicates when an access to the internal hard disk is occurring.
  - The **USER1** LED is a bi-color green/yellow LED. You can define the USER1 LED to meet the needs of your LabVIEW application.
  - The **USER2** LED is a bi-color green/yellow LED. You can define the USER2 LED to meet the needs of your LabVIEW application.

Data Storage

The NI PXIe-8135 has the following data storage features:

- Internal Serial ATA hard drive
  - 250 GB or larger 2.5 in. notebook hard drive
  - Supports Native Command Queuing
  - Supports transfer rates up to 600 MB/s
- Removable Serial ATA hard drive (Removable hard drive variant only)
  - 250 GB or larger 2.5 in. notebook hard drive
  - Supports Native Command Queuing
  - Supports transfer rates up to 300 MB/s
- USB storage support—USB CD/DVD-ROM, mass storage device, or floppy drive
Common Configuration Questions

This chapter answers common configuration questions you may have when using a NI PXIe-8135 embedded controller.

General Questions

What do the LEDs on the NI PXIe-8135 front panel mean?
Refer to the LED status descriptions in the Removable Hard Drive (Optional) section of Chapter 3, I/O Information.

After shutting down my NI PXIe-8135 controller, the Port 1 Ethernet LEDs continue to blink. Is it safe to remove my controller or disconnect power?
The NI PXIe-8135’s port 1 Intel 82579 Ethernet device remains powered even after shutdown. It is safe to remove your controller or disconnect power.

How do I check the configuration of the memory, hard drive, time/date, and so on?
You can view these parameters in the BIOS setup. To enter the BIOS setup, reboot the NI PXIe-8135 and press <Delete> during the memory tests. Refer to the Accessing BIOS Setup Utility section of Chapter 2, Installation and Configuration, for more information.

Can I use the internal Serial ATA drive and an external hard drive at the same time?
Yes. Refer to the BIOS Setup Utility section of Chapter 2, Installation and Configuration, for more information.

Boot Options

What devices can I boot from?
The NI PXIe-8135 can boot from the following devices:

• The internal Serial ATA hard drive
• An external SCSI hard drive or SCSI CD/DVD-ROM if a SCSI adapter, such as the PXI-8214, is used
• A network PXE server on the same subnet
An external USB mass storage device such as a USB hard drive, USB CD/DVD-ROM, or USB flash drive
- An external USB floppy drive
- Most PCI or PCIe-based devices that provide an Option ROM

**Note** There are some limitations when booting from a USB device. Windows 7 and Windows XP can be installed from a USB CD/DVD-ROM, but earlier versions of Windows cannot. The NI PXIe-8135 BIOS configures the USB devices so that they will work in a DOS environment.

**How do I configure the controller to boot from these devices?**

There are two methods.
- Enter the BIOS setup by rebooting the controller and pressing <Delete> during the memory tests. Select the **Boot** menu. You will see a list of all bootable devices, ordered by device type. You can set the boot order by altering the **1st Boot Device**, **2nd Boot Device**, and **3rd Boot Device** settings.
- To boot from a different device without permanently changing the boot order, press <F10> during POST. After the BIOS completes the POST and just before the controller boots the OS, the **Boot** menu is displayed. You can select the device type you want to boot from.

**Cables and Connections**

**How do I plug both a PS/2 mouse and PS/2 keyboard into the controller?**

The NI PXIe-8135 has no PS/2 connector, and you need to use a USB Y-splitter cable as shown in Figure 4-1, or a similar device, to connect both a PS/2 mouse and PS/2 keyboard. National Instruments part number 778713-01 is such a cable and is available through the online catalog at ni.com/products.

![Figure 4-1. Y-Splitter Cable](image)

**What if I don’t have a Y-splitter cable? Can I still use a mouse and keyboard?**

If you do not have a Y-splitter cable, plug a USB keyboard into any USB connector. You can also plug a USB mouse into any USB connector.
How do I connect a standard 25-pin LPT cable to the NI PXIe-8135?

The NI PXIe-8135 uses a type C LPT connector. Most parallel port devices use a type A connector. To use a device with a standard type A LPT connector, you need to use a type C-to-type A LPT adapter. Parallel port adapter cables, part number 777169-01, are available through the online catalog at ni.com/products.

Software Driver Installation

How do I install or reinstall the video driver?

Refer to KnowledgeBase 3H3COSD8, What Peripheral Drivers Should I Use with My PXI or VXI Controller?, at ni.com/support.

How do I install or reinstall the Ethernet driver?

Refer to KnowledgeBase 3H3COSD8, What Peripheral Drivers Should I Use with My PXI or VXI Controller?, at ni.com/support.

How do I install or reinstall the GPIB driver?

The NI-488.2 driver for your GPIB port is installed by default when your controller is first shipped from the factory. To change the default installed driver, complete the following steps:

1. Download the latest GPIB driver from ni.com/downloads.
2. Install the driver and verify that the driver has properly detected the GPIB driver in the Device Manager. If you need more assistance, refer to ni.com/support/install.

How do I install software from a CD?

The compact size of the NI PXIe-8135 does not allow for an integrated USB CD/DVD-ROM drive. If you are using Windows 7 or Windows XP, you have the following options:

- **USB CD/DVD-ROM**—Windows 7 and Windows XP support installing from a USB CD/DVD-ROM using a bootable installation CD.
- **SCSI CD-ROM**—Windows 7 and Windows XP support installing from a SCSI CD-ROM using a bootable installation CD.
- **Mapped network drive**—You can use the Ethernet to connect to another computer. If you share the USB CD/DVD-ROM drive on the other computer, you can map the shared USB CD/DVD-ROM drive to a drive letter on the NI PXIe-8135.

A USB CD/DVD-ROM drive is available from National Instruments, part number 778492-01.
Chapter 4  Common Configuration Questions

Upgrade Information

How do I upgrade system memory?

You can change the amount of installed RAM on the NI PXIe-8135 by upgrading the DDR3 SO-DIMMs.

To upgrade the RAM, remove the NI PXIe-8135 from the PXI Express chassis. To optimize both memory capacity and system performance, use the same size and speed memory module in each of the two module slots. The use of different size modules in each slot is supported, but system performance will be slower than using two matched modules. However, two mismatched modules will result in better performance than using a single module.

National Instruments offers the following types of SO-DIMMs for use with the NI PXIe-8135 controller.

- PC3-12800 (DDR3 1600) 4 GB, 256 MB × 64, CL 9, 1.18 in. max  
  (NI part number 782341-4096)
- PC3-12800 (DDR3 1600) 8 GB, 512 MB × 64, CL 9, 1.18 in. max  
  (NI part number 782341-8192)

Note  National Instruments has tested and verified that the DDR3 SO-DIMMs we sell work with the NI PXIe-8135. We recommend you purchase your DDR3 SO-DIMM modules from National Instruments. Other off-the-shelf DDR3 SO-DIMM modules are not guaranteed to work properly.

When installing memory modules into the memory sockets, the lower socket must be populated first, followed by the upper socket. If a single memory module is used, it must be installed in the lower socket.

The NI PXIe-8135 removable hard drive variant has a single module slot that supports up to an 8 GB DDR3 SO-DIMM module.
**How do I flash a new BIOS?**

You can download the new BIOS from ftp.ni.com/support/pxi. For more information, refer to KnowledgeBase 2GIGKD0Z, *Determining and Upgrading PXI and VXI Embedded Controller BIOS Versions*.

**Where do I get the latest software drivers?**

The latest National Instruments software is available from ni.com/downloads. For peripheral drivers, refer to KnowledgeBase 3H3COSD8, *What Peripheral Drivers Should I Use with My PXI or VXI Controller?*, at ni.com.

**My NI PXIe-8135 does not have an internal floppy drive. Is there a way to use an external drive?**

Yes. The NI PXIe-8135 controller supports and can boot from USB floppy drives. Refer to the *Boot Options* section for more information.

A USB floppy drive is available from National Instruments, part number 778492-02.
Chapter 4  Common Configuration Questions

PXI Express Configuration

How do I use the SMB trigger on the front panel?
For details, refer to the PXI Express Features section of Chapter 2, Installation and Configuration.

Why doesn't the NI PXIe-8135 work with the PXI-8220 or PXI-8221?
The serialized IRQ line is not routed to the Intel 7 Series chipset on the NI PXIe-8135. This prevents PC cards using ISA interrupts from working with the NI PXIe-8135.
This chapter answers common troubleshooting questions you may have when using the NI PXIe-8135 embedded computer.

What if the NI PXIe-8135 does not boot?

Several problems can cause a controller not to boot. Here are some things to look for and possible solutions.

Things to Notice:

- Which LEDs come on? The PWROK/FAULT LED should stay lit green. The Drive LED should blink during boot as the disk is accessed.
- What appears on the display? Does it hang at some particular point (BIOS, Operating System, and so on)? If nothing appears on the screen, try a different monitor. Does your monitor work with a different PC? If it hangs, note the last screen output that you saw for reference when consulting National Instruments technical support.
- What has changed about the system? Did you recently move the system? Was there electrical storm activity? Did you recently add a new module, memory chip, or piece of software?
- Refer to your chassis user manual for additional troubleshooting steps.

Things to Try:

- Make sure the chassis is plugged into a working power source.
- Check any fuses or circuit breakers in the chassis or other power supply (possibly a UPS).
- Make sure the controller module is firmly seated in the chassis.
- Remove all other modules from the chassis.
- Remove any nonessential cables or devices.
- Try the controller in a different chassis.
- Try a similar controller in this same chassis.
- Clear the CMOS. (Refer to the System CMOS section of Chapter 2, Installation and Configuration.)
- Recover the hard drive on the controller. (Refer to the Hard Drive Recovery section of Chapter 2, Installation and Configuration.)
- Make sure the RAM is properly seated.
- For the removable hard drive variant, ensure the HDD shuttle is properly seated.
Chapter 5  Troubleshooting

My controller boots fine until I get to Windows, at which point I cannot read the screen. This may include garbled output, white screen, black screen, or an out of synch message from the monitor.

This problem usually results from having the video card output set past the limits of the monitor. You will need to boot Windows in Safe Mode. To do this, reboot the controller. As Windows begins to boot, hold down <F8>. You should now be able to reset the video driver to lower settings. Try setting the resolution to 800 × 600 and the refresh rate to 60 Hz. Once you reboot, you can raise these values again, using the test option in Windows. These settings are accessible through the Advanced tab of the Display item in the Control Panel. Alternately, you can try a different monitor, preferably a newer and larger one.

My system boots fine as long as a particular module is not in my chassis.

The most common cause of this is a damaged module. Try the module in a different chassis or with a different controller. Also, remove any external cables or terminal blocks connected to the system. If the module does not work in these cases, it is likely damaged. Contact the module manufacturer for further troubleshooting.

Refer to the KnowledgeBase or product manuals section at ni.com for more information specific to the chassis and controller with which you are having difficulties.

My CMOS is corrupted. How do I set it back to default?

1. Enter the BIOS setup program as described in the Accessing BIOS Setup Utility section of Chapter 2, Installation and Configuration.
2. Press <F9> to load BIOS defaults.
3. Answer Y (Yes) to the verification prompt.
4. Select Save and Exit Setup.

As an alternative method, complete the following steps:
1. Power off the chassis.
2. Remove the controller from the chassis.
3. Press the Clear CMOS button (SW2) as shown in Figure 5-1.
4. Wait ten seconds.
5. Reinstall the controller in the chassis.
Figure 5-1. Clearing the CMOS Contents

1 Push-Button Switch SW2
Specifications

This appendix lists the electrical, mechanical, and environmental specifications of the NI PXIe-8135 embedded controller.

Features

<table>
<thead>
<tr>
<th>Feature</th>
<th>Specification</th>
</tr>
</thead>
<tbody>
<tr>
<td>CPU</td>
<td>Intel Core i7 3610 QE</td>
</tr>
<tr>
<td>CPU Frequency</td>
<td>2.3 GHz (base), 3.3 GHz (single-core Turbo mode)</td>
</tr>
<tr>
<td>On-die L2 cache</td>
<td>256 KB x4 (256 KB per core)</td>
</tr>
<tr>
<td>Dual-Channel DDR3 RAM, PC3 12800</td>
<td>4 GB Standard, 16 GB Maximum</td>
</tr>
<tr>
<td>Single-Channel DDR3 RAM, PC3 12800*</td>
<td>4 GB Standard, 8 GB Maximum</td>
</tr>
<tr>
<td>Hard Drive</td>
<td>250 GB or larger Serial ATA†</td>
</tr>
<tr>
<td>Ethernet</td>
<td>10/100/1000 BaseTX, 2 ports</td>
</tr>
<tr>
<td>PXI Express 4 Link Configuration</td>
<td>x4, x4, x4, x4</td>
</tr>
<tr>
<td>PXI Express 2 Link Configuration</td>
<td>x8, x8</td>
</tr>
<tr>
<td>GPIB (IEEE 488 Controller)</td>
<td>Yes</td>
</tr>
<tr>
<td>Serial Ports (RS-232)</td>
<td>Yes (1)</td>
</tr>
<tr>
<td>Parallel Port</td>
<td>Yes (1)</td>
</tr>
<tr>
<td>Hi-Speed USB (2.0) Ports</td>
<td>Yes (4)</td>
</tr>
<tr>
<td>Hi-Speed USB (3.0) Ports</td>
<td>Yes (2)</td>
</tr>
<tr>
<td>ExpressCard/34 Slot</td>
<td>Yes</td>
</tr>
<tr>
<td>PS/2 Keyboard/Mouse Connector</td>
<td>No</td>
</tr>
<tr>
<td>PXI Express Trigger Bus Input/Output</td>
<td>Yes</td>
</tr>
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</table>
Appendix A Specifications

### NI PXIe-8135

<table>
<thead>
<tr>
<th>Removable Hard Drive</th>
<th>Yes (1)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Installed Operating System</td>
<td>Windows 7 Professional, Windows XP Professional SP3 for Embedded Systems</td>
</tr>
</tbody>
</table>

* Removable hard drive option.

† Extended-temperature 24/7 option provides 80 GB minimum hard drive. Controllers configured for LabVIEW RT provide a 80 GB (minimum) SATA hard drive.

### Electrical

<table>
<thead>
<tr>
<th>Voltage (V)</th>
<th>Typical (A)</th>
<th>Maximum (A)</th>
</tr>
</thead>
<tbody>
<tr>
<td>+3.3 V</td>
<td>3.75</td>
<td>5.4</td>
</tr>
<tr>
<td>+5 V</td>
<td>1.5</td>
<td>2.0</td>
</tr>
<tr>
<td>+12 V</td>
<td>3.5</td>
<td>5.0</td>
</tr>
<tr>
<td>-12 V</td>
<td>0.00</td>
<td>0.00</td>
</tr>
<tr>
<td>+5 V Aux</td>
<td>0.3</td>
<td>0.4</td>
</tr>
</tbody>
</table>

### Physical

Board dimensions: Four-wide 3U PXI Express module
Slot requirements: One system slot plus three controller expansion slots
Compatibility: Fully compatible with PXI Express Specification 1.0
Weight: 1.30 kg (2.87 lb) typical

### Environment

Maximum altitude: 2,000 m (800 mbar) at 25 °C ambient temperature
Pollution Degree: 2
Indoor use only.

⚠️ Caution: Clean the NI PXIe-8135 with a soft nonmetallic brush. Make sure that the device is completely dry and free from contaminants before returning it to service.
Operating Environment

NI PXIe-8135

Ambient temperature range

Standard............................................ 5 to 50 °C
(Tested in accordance with IEC-60068-2-1 and IEC-60068-2-2. Meets MIL-PRF-28800F Class 3 high temperature limit.)

Extended Temperature
Option............................................... 0 to 55 °C
(Tested in accordance with IEC-60068-2-1 and IEC-60068-2-2. Meets MIL-PRF-28800F Class 3 low temperature limit and MIL-PRF-28800F Class 2 high temperature limit.)

Relative humidity range............................ 10% to 90%, noncondensing
(Tested in accordance with IEC-60068-2-56.)

Caution The operating temperature must not be exceeded, even when used in a chassis with a higher temperature range.

Storage Environment

NI PXIe-8135

Ambient temperature range

Standard............................................ -40 to 65 °C
(Tested in accordance with IEC-60068-2-1 and IEC-60068-2-2. Meets MIL-PRF-28800F Class 3 low temperature limit.)

Extended Temperature
Option............................................... -40 to 71 °C
(Tested in accordance with IEC-60068-2-1 and IEC-60068-2-2. Meets MIL-PRF-28800F Class 3 limits.)

Relative humidity range............................ 5% to 95%, noncondensing
(Tested in accordance with IEC-60068-2-56.)

Shock and Vibration

Operating Shock ....................................... 30 g peak, half-sine, 11 ms pulse
(Tested in accordance with IEC-60068-2-27. Meets MIL-PRF-28800F Class 2 limits.)

---

1 Processor should not throttle CPU frequency under reasonable, worst case processor work loads in high operating temperatures.
Appendix A Specifications

Random Vibration

Operating .................................................. 5 to 500 Hz, 0.3 g_{rms} (with solid-state hard drive)
Nonoperating ............................................ 5 to 500 Hz, 2.4 g_{rms}

(Tested in accordance with IEC-60068-2-64. Nonoperating test profile exceeds the requirements of MIL-PRF-28800F, Class 3.)

Note Specifications are subject to change without notice.

Safety

This product is designed to meet the requirements of the following standards of safety for electrical equipment for measurement, control, and laboratory use:

• IEC 61010-1, EN 61010-1
• UL 61010-1, CSA 61010-1

Note For UL and other safety certifications, refer to the product label or the Online Product Certification section.

Caution Using the NI PXIe-8135 in a manner not described in this document may impair the protection the NI PXIe-8135 provides.

Electromagnetic Compatibility

This product meets the requirements of the following EMC standards for electrical equipment for measurement, control, and laboratory use:

• EN 61326-1 (IEC 61326-1): Class A emissions; Basic immunity
• EN 55011 (CISPR 11): Group 1, Class A emissions
• AS/NZS CISPR 11: Group 1, Class A emissions
• FCC 47 CFR Part 15B: Class A emissions
• ICES-001: Class A emissions

Note In the United States (per FCC 47 CFR), Class A equipment is intended for use in commercial, light-industrial, and heavy-industrial locations. In Europe, Canada, Australia and New Zealand (per CISPR 11) Class A equipment is intended for use only in heavy-industrial locations.

Note Group 1 equipment (per CISPR 11) is any industrial, scientific, or medical equipment that does not intentionally generates radio frequency energy for the treatment of material or inspection/analysis purposes.

Note For EMC declarations and certifications, and additional information, refer to the Online Product Certification section.
CE Compliance

This product meets the essential requirements of applicable European Directives as follows:

- 2006/95/EC; Low-Voltage Directive (safety)
- 2004/108/EC; Electromagnetic Compatibility Directive (EMC)

Online Product Certification

To obtain product certifications and the Declaration of Conformity (DoC) for this product, visit ni.com/certification, search by model number or product line, and click the appropriate link in the Certification column.

Environmental Management

NI is committed to designing and manufacturing products in an environmentally responsible manner. NI recognizes that eliminating certain hazardous substances from our products is beneficial to the environment and to NI customers.

For additional environmental information, refer to the Minimize Our Environmental Impact Web page at ni.com/environment. This page contains the environmental regulations and directives with which NI complies, as well as other environmental information not included in this document.

Waste Electrical and Electronic Equipment (WEEE)

EU Customers

At the end of the product life cycle, all products must be sent to a WEEE recycling center. For more information about WEEE recycling centers, National Instruments WEEE initiatives, and compliance with WEEE Directive 2002/96/EC on Waste and Electronic Equipment, visit ni.com/environment/weee.

Battery Replacement and Disposal

Battery Directive

This device contains a long-life coin cell battery. If you need to replace it, use the Return Material Authorization (RMA) process or contact an authorized National Instruments service representative. For more information about compliance with the EU Battery Directive 2006/66/EC about Batteries and Accumulators and Waste Batteries and Accumulators, visit ni.com/environment/batterydirective.

电子信息产品污染控制管理办法 （中国 RoHS）

电子信息产品污染控制管理办法 （中国 RoHS）

中国客户 National Instruments 符合电子信息产品中限制使用某些有害物质指令 (RoHS)。关于 National Instruments 中国 RoHS 合规性信息，请登录 ni.com/environment/rohs_china。 (For information about China RoHS compliance, go to ni.com/environment/rohs_china.)
Technical Support and Professional Services

Log in to your National Instruments ni.com User Profile to get personalized access to your services. Visit the following sections of ni.com for technical support and professional services:

• **Support**—Technical support at ni.com/support includes the following resources:
  – **Self-Help Technical Resources**—For answers and solutions, visit ni.com/support for software drivers and updates, a searchable KnowledgeBase, product manuals, step-by-step troubleshooting wizards, thousands of example programs, tutorials, application notes, instrument drivers, and so on. Registered users also receive access to the NI Discussion Forums at ni.com/forums. NI Applications Engineers make sure every question submitted online receives an answer.
  – **Standard Service Program Membership**—This program entitles members to direct access to NI Applications Engineers via phone and email for one-to-one technical support, as well as exclusive access to self-paced online training modules at ni.com/self-paced-training. All customers automatically receive a one-year membership in the Standard Service Program (SSP) with the purchase of most software products and bundles including NI Developer Suite. NI also offers flexible extended contract options that guarantee your SSP benefits are available without interruption for as long as you need them. Visit ni.com/ssp for more information.

For information about other technical support options in your area, visit ni.com/services, or contact your local office at ni.com/contact.

• **Training and Certification**—Visit ni.com/training for training and certification program information. You can also register for instructor-led, hands-on courses at locations around the world.

• **System Integration**—If you have time constraints, limited in-house technical resources, or other project challenges, National Instruments Alliance Partner members can help. To learn more, call your local NI office or visit ni.com/alliance.

• **Declaration of Conformity (DoC)**—A DoC is our claim of compliance with the Council of the European Communities using the manufacturer’s declaration of conformity. This system affords the user protection for electromagnetic compatibility (EMC) and product safety. You can obtain the DoC for your product by visiting ni.com/certification.

• **Calibration Certificate**—If your product supports calibration, you can obtain the calibration certificate for your product at ni.com/calibration.
Appendix B  Technical Support and Professional Services

You also can visit the Worldwide Offices section of ni.com/niglobal to access the branch office Web sites, which provide up-to-date contact information, support phone numbers, email addresses, and current events.
Glossary

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<th>Symbol</th>
<th>Prefix</th>
<th>Value</th>
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<tr>
<td>n</td>
<td>nano</td>
<td>$10^{-9}$</td>
</tr>
<tr>
<td>$\mu$</td>
<td>micro</td>
<td>$10^{-6}$</td>
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<tr>
<td>m</td>
<td>milli</td>
<td>$10^{-3}$</td>
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<tr>
<td>k</td>
<td>kilo</td>
<td>$10^3$</td>
</tr>
<tr>
<td>M</td>
<td>mega</td>
<td>$10^6$</td>
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<tr>
<td>G</td>
<td>giga</td>
<td>$10^9$</td>
</tr>
<tr>
<td>T</td>
<td>tera</td>
<td>$10^{12}$</td>
</tr>
</tbody>
</table>

Symbols

° Degrees.
Ω Ohms.
% Percent.

A

A Amperes.
AC Alternating Current.

B

B Bytes.

backplane An assembly, typically a printed circuit board, with connectors and signal paths that bus the connector pins.

BIOS Basic Input/Output System—BIOS functions are the fundamental level of any PC or compatible computer. BIOS functions embody the basic operations needed for successful use of the computer’s hardware resources.
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<tr>
<td>cache</td>
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<tr>
<td>CMOS</td>
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<tr>
<td>CompactPCI Express</td>
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<tr>
<td>DC</td>
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<td>DDR</td>
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<tr>
<td>DMA</td>
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<tr>
<td>DVI</td>
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<tr>
<td><strong>E</strong></td>
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<tr>
<td>ECP</td>
</tr>
<tr>
<td>EEPROM</td>
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<tr>
<td>EMC</td>
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<tr>
<td>EMI</td>
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</table>
EPP | Enhanced Parallel Port.

expansion ROM | An onboard EEPROM that may contain device-specific initialization and system boot functionality.

F

FCC | Federal Communications Commission.

G

g | 1. Grams.
2. A measure of acceleration equal to 9.8 m/s².

GPIB | General Purpose Interface Bus (IEEE 488).

g_{rms} | A measure of random vibration—The root mean square of acceleration levels in a random vibration test profile.

H

Hz | Hertz—Cycles per second.

I

I/O | Input/Output—The techniques, media, and devices used to achieve communication between machines and users.

IDE | Integrated Drive Electronics—Hard disk and built-in controller.

IEEE | Institute of Electrical and Electronics Engineers.

in. | Inches.

instrument driver | A set of routines designed to control a specific instrument or family of instruments, and any necessary related files for LabWindows/CVI or LabVIEW.

interrupt | A means for a device to request service from another device.

interrupt level | The relative priority at which a device can interrupt.
**Glossary**

<table>
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<th>Definition</th>
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<td>IRQ#</td>
<td>Interrupt signal.</td>
</tr>
<tr>
<td>ISA</td>
<td>Industry Standard Architecture—The original PC bus architecture, specifically the 16-bit AT bus.</td>
</tr>
<tr>
<td>K</td>
<td>Kilobytes of memory.</td>
</tr>
<tr>
<td>LAN</td>
<td>Local Area Network—Communications network that serves users within a confined geographical area. It is made up of servers, workstations, a network operating system, and a communications link.</td>
</tr>
<tr>
<td>LED</td>
<td>Light-emitting diode.</td>
</tr>
<tr>
<td>M</td>
<td>Meters.</td>
</tr>
<tr>
<td>master</td>
<td>A functional part of a PXI Express device that initiates data transfers on the PXI Express backplane. A transfer can be either a read or a write.</td>
</tr>
<tr>
<td>MB</td>
<td>Megabytes of memory.</td>
</tr>
<tr>
<td>MTBF</td>
<td>Mean time between failure.</td>
</tr>
<tr>
<td>N</td>
<td>The National Instruments software for GPIB systems.</td>
</tr>
<tr>
<td>NI-488 or NI-488.2</td>
<td>The National Instruments software for data acquisition instruments.</td>
</tr>
<tr>
<td>NI-DAQ</td>
<td>The National Instruments implementation of the VISA standard—an interface-independent software that provides a unified programming interface for VXI, GPIB, and serial instruments.</td>
</tr>
</tbody>
</table>

Peripheral Component Interconnect—The PCI bus is a high-performance 32-bit or 64-bit bus with multiplexed address and data lines.

Personal Computer Memory Card International Association.

Any hardware device connected to a computer, such as a monitor, keyboard, printer, plotter, disk or tape drive, graphics tablet, scanner, mouse, and so on.

PCI eXtensions for Instrumentation—An open implementation of CompactPCI Express that adds electrical features that meet the high-performance requirements of instrumentation applications by providing triggering, local buses, and system clock capabilities. PXI Express also offers two-way interoperability with CompactPCI Express products.

Random Access Memory—The computer’s primary workspace.

Hardware settings used by devices in a computer system, including ISA interrupt level, DMA channel, and I/O address.

Root mean squared. See also \( g_{rms} \).

Seconds.

Synchronous Dynamic RAM (Random Access Memory)—Storage that the computer must refresh at frequent intervals.

Small Outline Dual In-line Memory Module.

Serial Peripheral Interface—A standard for controlling most any digital electronics that accept a clocked serial stream of bits.
## Glossary

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<th>U</th>
<th><strong>USB</strong></th>
<th>Universal Serial Bus.</th>
</tr>
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<tr>
<td>V</td>
<td><strong>V</strong></td>
<td>Volts.</td>
</tr>
<tr>
<td></td>
<td><strong>VGA</strong></td>
<td>Video Graphics Array—The minimum video display standard for all PCs.</td>
</tr>
<tr>
<td>W</td>
<td><strong>W</strong></td>
<td>Watts.</td>
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